USER'S MANUAL SINGLE HEAD LCD CONTROLLER TYPE TEHX-C

M-EHXC-SLCD-04-E (2003.10)

FOREWORD

This manual is a guidebook for using TAJIMA automatic embroidery machine TEHX-C (referred to as machine hereafter) correctly. Items to notice when using the machine are described. Please read this manual thoroughly, understand the contents, and then use the machine.

The contents of this manual are largely divided into the following sections.

[IMPORTANT WARNING ITEMS FOR SAFE OPERATION] [MACHINE CONSTRUCTION] [OPERATION BASICS] [DATA SETTING] [EMBROIDERY SETTING] [DESIGN DATA MANAGEMENT] [MANUAL OPERATION] [PARAMETER SETTING] [OUTLINE OF FUNCTIONS] [ELECTRO-COMPONENT PARTS] [TROUBLESHOOTING] [MAINTENANCE] [APPENDIX]

Regarding optional devices, please refer to the user's manual of the device you have selected. This manual may contain discrepancies in detailed information when compared with the product due to continued research and improvements. If any question about the product or the contents of this manual arises, please consult your TAJIMA distributor. Please keep this manual near the machine for immediate reference. When this manual is not used, keep it carefully.

Tokai Industrial Sewing Machine Co., Ltd.

IMPORTANT SAFETY INSTRUC-TIONS

Operation of this machine requires correct operation and appropriate maintenance to ensure safety. Please read the IMPORTANT SAFETY INSTRUCTIONS in this manual carefully and do not attempt operation or maintenance of the machine before you thoroughly understand the items written under IMPORTANT SAFETY INSTRUCTIONS. Items that require your special attention on operation and maintenance of the machine are specified below with the warning symbol and signal word. These items must be strictly observed to ensure safety during operation and maintenance. Signal word definition is given below.

DANGER

Indicates that there is a lot of danger or death or serious injuries [*1] if the instruction is not observed.

WARNING

Indicates that there is a likelihood of death or serious injuries [*1] if the instruction is not observed.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury [*2] or property damage.

*1:A condition caused by electric shock, injury, fracture of a bone, etc., that leads to aftereffects, or an injury that necessitates hospitalization or visits to a hospital over a long period.

*2: An injury that does not necessitate hospitalization or visit to a hospital over a long period.



Prohibited items

Items that may cause electric shock if not observed

Items that must be followed carefully to ensure safe operation

- \bigwedge : Items that must be observed to perform works comfortably
- : Items that explain the contents of sentences in detail and items that complement the contents.

FOREWORD IMPORTANT SAFETY INSTRUCTIONS

CHAPTER 1 IMPORTANT WARNING ITEMS FOR SAFE OPERATION

1.	INSTALLATION ENVIRONMENT	2
2.	CAUTIONS ON MACHINE OPERATION	3
3.	WARNING LABELS	5

CHAPTER 2 MACHINE CONSTRUCTION

1.	MAIN FUNCTIONS	8
	NAME OF EACH PART	
	ELECTRICAL SPECIFICATIONS	
4.	OPERATION PANEL BOX 1	0
	TENSION BASE 1	

CHAPTER 3 OPERATION BASICS

1. POWER SWITCH	12
2. EMERGENCY STOP SWITCH	12
3. START/STOP SWITCH	12
4. FLOPPY DISK AND FDD	13
5. CPU SOFTWARE INSTALLATION	14
6. PANEL SOFTWARE INSTALLATION	15
7. OPERATION FLOW	17
8. VALUE INPUT	
9. INPUT OF CHARACTERS	
10. EXPLANATION ON THE SCREEN (SCREEN 1000)	19
11. EXPLANATION ON THE SCREEN (SCREEN 1100)	19
12. INSPECTION BEFORE STARTING EMBROIDERY	20

CHAPTER **4** DATA SET

1. EXPLANATION ON THE SCREEN (SCREEN 2000)	22
2. DATA INPUT FROM FLOPPY DISK	23
3. DATA INPUT FROM SERIAL CONNECTION	24
4. DATA SET	25

CHAPTER 5 EMBROIDERY SETTING

1. EXPLANATION ON THE SCREEN (SCREEN 5000)	
2. CHANGE OF NEEDLE BAR	
3. DELETION OF NEEDLE BAR STEP	
4. INSERTION OF NEEDLE BAR STEP	
5. REPEAT OF NEEDLE BAR SETTING	
6. OFFSETTING AT AUTOMATIC COLOR CHANGE	33
7. NEEDLE BAR COLOR	
8. EXPLANATION ON THE SCREEN (SCREEN 6000)	
9. DESIGN SCALE UP/DOWN	
10. ROTATION/MIRROR IMAGE REVERSION	
11. REPEAT	
12. REPEAT (CONVERTED ARRANGEMENT)	40
13. EXPLANATION ON THE SCREEN (AUTOMATIC OFFSET)	41
14. AUTOMATIC OFFSET	42

CHAPTER 6 DESIGN DATA MANAGEMENT

1.	EXPLANATION ON THE SCREEN (SCREEN 2200)	44
2.	FLOPPY DISK WRITING	45
3.	OVERWRITING OF DESIGN NAME	46
4.	DELETION OF MEMORY DESIGN	47

5. DELETION OF ALL DESIGNS	
6. CLEANUP	49
7. EXPLANATION ON THE SCREEN (SCREEN 8000)	50
8. FUNCTION SEARCH	
9. INSERTION OF STITCH	
10. DELETION OF STITCH	53
11. MODIFICATION OF STITCH DATA	
12. EXPLANATION ON THE SCREEN (SCREEN 3000)	55
13. DELETION OF DESIGN DATA IN FLOPPY DISK	56
14. FORMATTING OF FLOPPY DISK	57

CHAPTER 7 MANUAL OPERATION

1. EXPLANATION ON THE SCREEN (SCREEN 1400)	60
2. THREAD TRIMMING/TRACE	61
3. MANUAL OFFSET/DESIGN START POSITION	62
4. FRAME ORIGIN MEMORY	63
5. POWER RESUME	64
6. FRAME BACK/FORWARD	65
7. COLOR CHANGE (SCREEN 1300)	66

CHAPTER 8 PARAMETER SETTING

1. AUTO COLOR CHANGE (AC)	69
2. AUTO START (AS)	69
3. A.S. IN THE SAME COLOR	69
4. A. S. AFTER AUTO DATA SET	69
5. MAIN SHAFT INCHING	
6. M.SHAFT INCHING AFTER ATH	
7. AUTO JUMP [MM]	
8. JUMP CONVERT	70
15. MIN. REVOLUTION [RPM]	71
16. UPPER T.DETECTION	72
17. UNDER T.DETECTION (UNIT)	72
18. UNDER T.D. (STEP RATIO) [%]	72
19. ATH	72
20. PICKER TIMING (TAIL LENGTH)	72
21. SELECT UNDER T. TRIMMING [MM]	73
22. RETURN STITCHES (ATH)	73
23. TIE STITCHES	73
24. TIE/RETURN STITCH LENGTH [MM]	73
25. PRESET HALT (STITCH)	73
26. PRESET HALT (DATA)	74
27. PRESET HALT (DESIGN)	74
28. PRESET HALT (LUBRICATION)	74
29. PRESET HALT (JUST BEFORE END CODE)	74
30. LANGUAGE	74
31. F.B/F.F. STITCH UNIT [ST]	75
32. SATIN STITCH (DATA TO ADD) [MM]	75
33. AUTO ORIGIN RETURN	75
34. FRAME TRAVEL SPEED [MM/SEC]	75
35. FRAME START TIMING [DEGREE]	75
41. BORING	77
42. BORING STEP	77
43. CORDING	77
45. NETWORK	77
46. SERIAL SPEED [BPS]	
47. ATH START TIMING [DEGREE]	78
49. BACKLASH (X AXIS) [MM]	

50. BACKLASH (Y AXIS) [MM]	78
51. TOTAL STITCH COUNTER	
52. DISPLAY OF M.SHAFT STOP POSITION	79
53. DISPLAY OF NEEDLE POSITION	79
54. PANEL SOFTWARE INSTALL	79
55. DISPLAY OF ATH POSITION	79
56. STOP AT LOWER D.POINT	80
57. FRAME TRAVEL KEY	80
58. ADJUST M. SHAFT STOP POSITION	80
61. MAX. REVOLUTION [RPM]	81
64. NUMBER OF NEEDLES	
67. FRAME DRIVE MODE	82
69. CPU SOFTWARE VERSION	82
69. CPU SOF I WARE VERSION	82

CHAPTER 9 OUTLINE OF FUNCTIONS

1. DESIGN SCALE UP/DOWN	
2. ROTATION	
3. MIRROR IMAGE REVERSION	84
4. REPEAT	85
5. CONVERTED ARRANGEMENT	85
6. MANUAL OFFSET	86
7. AUTOMATIC OFFSET	86
8. OFFSETTING AT AUTOMATIC COLOR CHANGE	87
9. BACKLASH	87
10. SATIN STITCH	88
11. TRACE	

CHAPTER 10 ELECTRO-COMPONENT PARTS

1. POWER SUPPLY/DRIVER UNIT	90
2. DIP SWITCH	90
3. SWITCHING OF POWER SUPPLY SPECIFICATION	91
4. OPERATION PANEL BOX	91

CHAPTER 11 TROUBLESHOOTING

1. IF MACHINE OPERATION IS INTERRUPTED	94	
2 IF TROUBLE OCCURS	97	

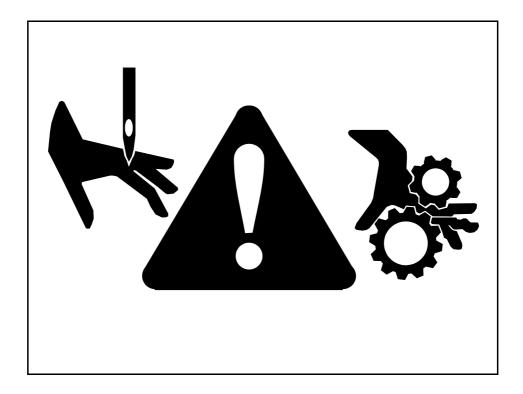
CHAPTER 12 MAINTENANCE

1. WARNINGS AND PRECAUTIONS	00
2. CLEANING	01
3. LUBRICATION	02
4. GREASING	03
5. INSPECTIONS	04
6. REPAIR	04

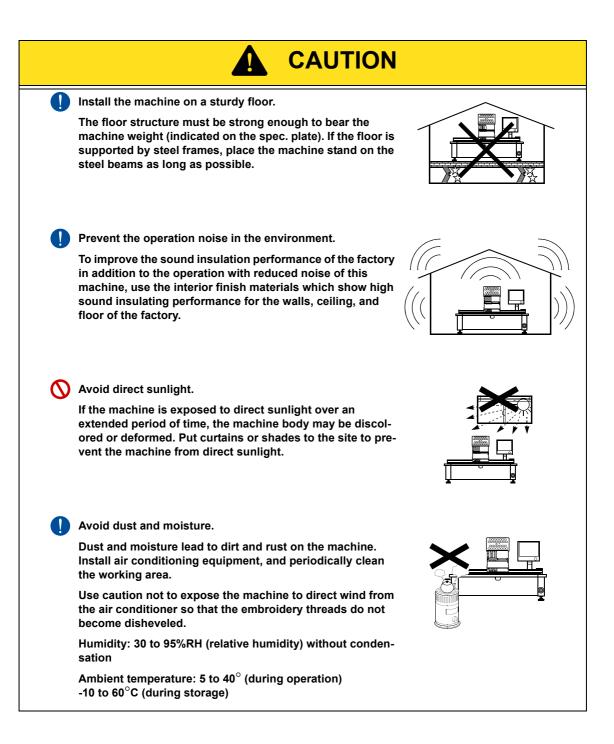
ELECTRO-RELATIVE DRAWING

CONTENTS

CHAPTER 1 IMPORTANT WARNING ITEMS FOR SAFE OPERATION



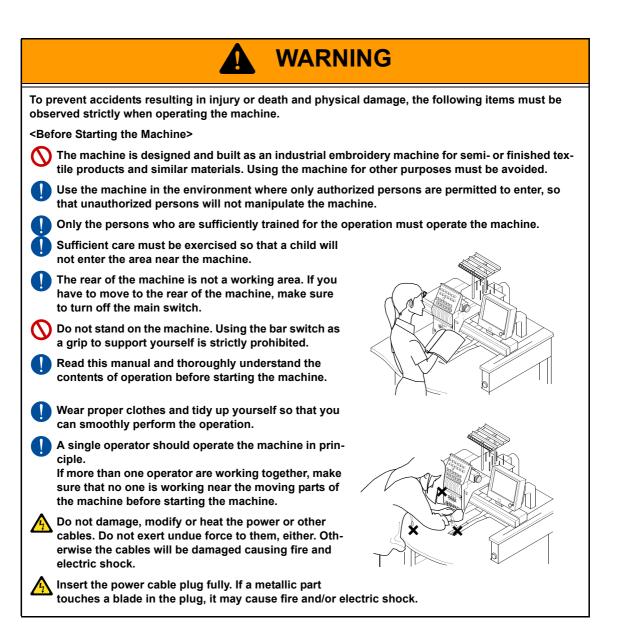
1. INSTALLATION ENVIRONMENT

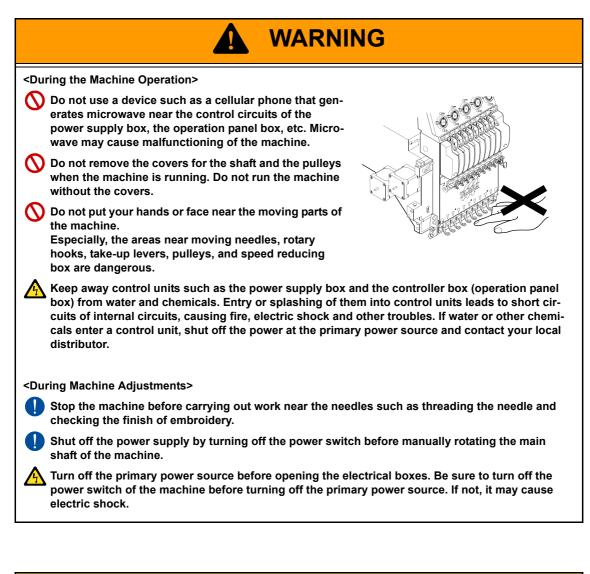


з

2. CAUTIONS ON MACHINE OPERATION

For long life machine operation, operate the machine with about 70% of the maximum speed as "operation for total fitting" for about one month after installation. By performing operation for total fitting, life of the machine will become longer, which will be useful to avoid unexpected troubles.





	ΓΙΟΝ	
When operating the machine, always observe the following items to prevent machine or property damage.		
O not use bent needles or those that do not fit the materials.		
After the completion of work, shut off the power source by turning off the switch of the power distributor panel.		
O not put things on the table.		
	<u> </u>	

3. WARNING LABELS

Important directive items

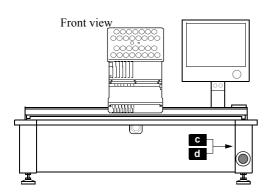
The machine has warning labels that bear instructions for safe operation. Machine operators must follow the instructions shown on the warning labels.

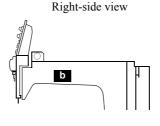
Do not detach the warning labels nor make them illegible by painting, etc.

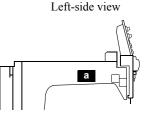
If a warning label is missed or damaged, please consult your local distributor.

Sticking position of the warning labels

For type of warning labels, refer to the next page.







5

Type of warning labels



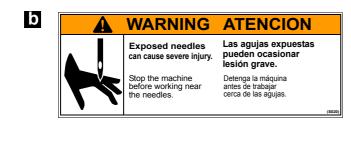




ni poner las manos, etc., cerca de las piezas en movimiento mientras la máquina esté

en funcionamiento

Regarding warning content of warning label (a), "safety cover" aims at all covers attached circumference of movable parts of the machine.

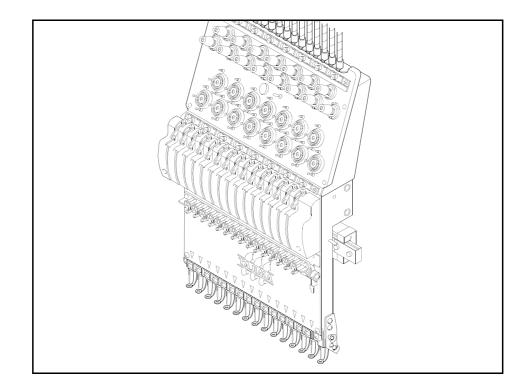


machine operation.





CHAPTER 2 MACHINE CONSTRUCTION



1. MAIN FUNCTIONS

♦EASY OPERATION

As the machine adopts touch panel type TFT color LCD and jog remote-controller (option), easy operation is obtained.

♦ POWER FAILURE MEASURE

It is possible to prevent the loss of products due to design displacement, etc. if power is shut off during machine operation.

CLEAN-UP FUNCTION

It disposes fine stitch data automatically to prevent skip stitches and thread breakage.

MEMORY

The machine is equipped with about 2,000,000 stitch memory as the standard, and it is possible to register up to 99 designs at the maximum.

◆TAKE-UP LEVER GUARD

It adds stability to thread movement, and prevents entangling of thread or coming-off of thread.

♦ENLARGE, REDUCE AND ROTATE DESIGN

It is possible to reduce/enlarge size of embroidery design within a range of 50 to 200% in increments of 1%. Rotation can be changed in increments of 1 degree.

AUTOMATIC REPEAT OPERATION

It is possible to set up to 99 times at the maximum for X and Y directions individually by inputting value for the number of repeats.

DESIGN DRAWING AT EMBROIDERING

It is possible to confirm the current embroidery position and progressing condition with real-time display.

BUILT-IN FLOPPY DISK DRIVE

A single 2DD floppy disk can store up to 111 designs with approximately 240,000 stitches. Alternatively, a 2HD floppy disk can hold up to 223 designs with approximately 480,000 stitches.

◆EDIT OF DESIGN DATA

Design can be edited (modified, inserted, deleted) in 1-stitch units.

FRAME BACK

The embroidery frame can be traveled back in 1-stitch units, color change code units, or by a designated number of stitches.

♦TRACE FUNCTION

The function checks if the design fits in the frame to be used before starting embroidery.

♦AUTOMATIC UPPER/UNDER THREAD TRIMMER

The machine trims thread automatically by command of design data. In addition, it is possible to activate automatic thread trimming and holding device manually to trim thread.

♦THREAD TENSION SUITABLE FOR HIGH-SPEED OPERATION

Highly stable thread tension is realized by the adoption of middle thread guide with tension spring and upper thread lock mechanism.

♦ROTARY TYPE THREAD BREAKAGE DETECTION MECHANISM

Stable detection of upper/under thread breakage is made possible even at high-speed operation.

QUIET OPERATION

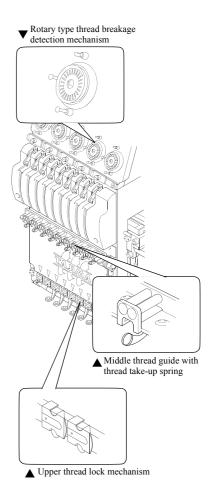
Variety of noise-reduction mechanism keeps working environment comfortable.

ORIGIN RETURN

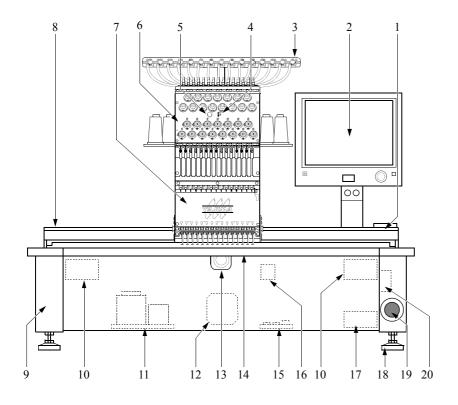
A return to the design origin (design start position/offset start position) can be made during embroidery operation, even if the design origin does not coincide with the design end point.



▲ Design drawing during embroidery



2. NAME OF EACH PART



3. ELECTRICAL SPECIFICATIONS

Electrical specifications of this machine are described below. Please use the machine complying with the condition.

If using the machine deviating from the conditions, trouble may occur.

Power supply

Electricity	330W (470VA)	
Voltage	Single phase 100 - 120 V/200 - 240 V	
Allowable voltage range	within $\pm 10\%$ of the rated voltage	
Frequency	50/60Hz	

Insulating resistor

10M ohms or larger (measured with a 500 V insulation tester)

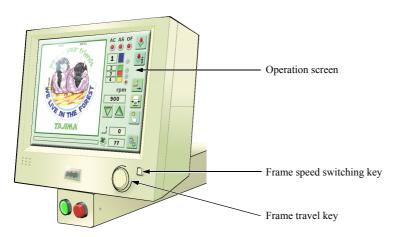


Since there is possibility of electric shock due to leak current, be sure to connect the grounding wire of the machine to the ground. Grounding resistance must be 100 ohms or less.

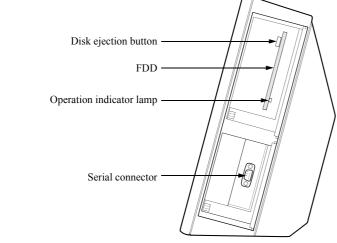
- 1. X-axis motor
- 2. Operation panel box
- 3. Thread guide system
- 4. Tension base switch
- 5. Thread breakage indicator lamp
- 6. Individual tension base
- 7. Needle bar case
- 8. Z-spec.frame
- 9. Stand
- 10. Y-axis motor
- 11. Power supply/Driver unit
- 12. Main shaft motor
- 13. Thread trimming cam box
- 14. Table
- 15. Joint card
- 16. ATH motor
- 17. Noise filter
- 18. Leveling adjuster
- 19. Emergency stop switch
- 20. Power switch

4. OPERATION PANEL BOX

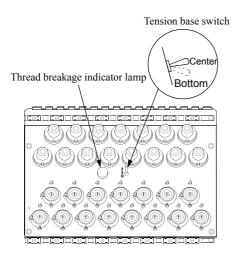
Operation screen (Touch panel)



<Right side of the panel>



5. TENSION BASE



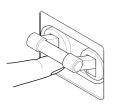
- For the protection of the screen, use the touch panel screen with protection film stuck.
- Do not touch the screen with sharp-pointed goods such as pen and pencil.
- ☐ Frame travel key It moves the embroidery frame to 4 directions/8 directions. → P.80
- Frame travel speed switching key It switches manual frame travel speed to low speed/high speed.

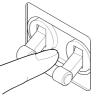
- Switch at the center: Usually, set the switch to "center" position.
- Switch at the bottom: The needle bar does not move. (Embroidery is not performed.)
- Thread breakage indicator lamp
 During normal operation: Green (lit)
 When upper thread breakage is detected:
 Red (lit)
 When under thread breakage is detected:
 Red (blinking)

CHAPTER 3 OPERATION BASICS



1. POWER SWITCH

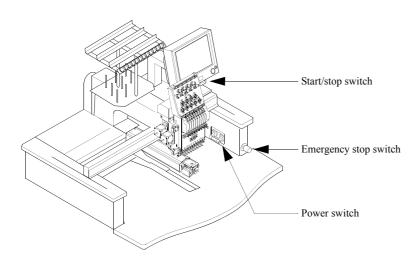




Turning "ON" the power"

Turning "OFF" the power"

2. EMERGENCY STOP SWITCH



3. START/STOP SWITCH





Start switch (green)

During stop

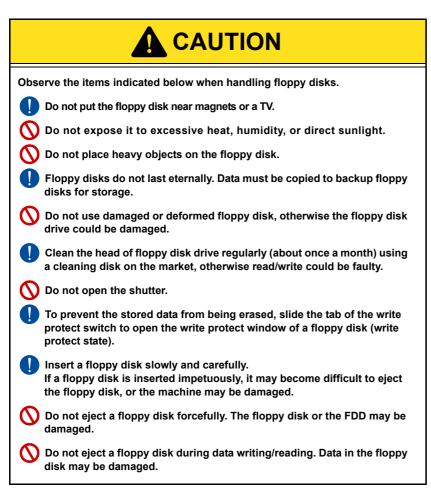
Stop switch (red)	Start switch (green)
Press the switch and release it.	Press the switch and release it.
FB/FF for 1 stitch is performed.	Operation starts
Keep pressing the switch.	Keep pressing the switch.
FB/FF for 1 stitch is performed.If it is released within 10 feeds, the motion stops at that point.If it is released with 11 feeds and more, the motion still continues and stops when it is pressed again.	Operation starts with inching ↓ Usual operation is performed when releasing it

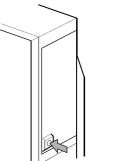
- When turning on the power again, turn "OFF" the switch and turn it "ON" after about 2 to 3 seconds.
- When the power is shut off such as power failure, the switch will be turned "OFF".

- Pressing the emergency stop switch will cause the machine to stop at the fixed position to turn OFF the power.
- Definition To release the lock, turn the switch knob to the direction indicated by the arrow.

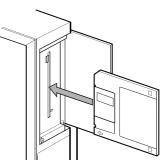
During operation Stop switch: stop Start switch: invalid

4. FLOPPY DISK AND FDD

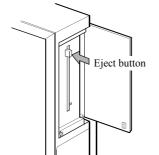




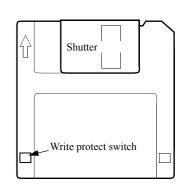
Push the part indicated by the arrow to open the cover.



Insert it as the illustration so that the arrow mark faces the front.

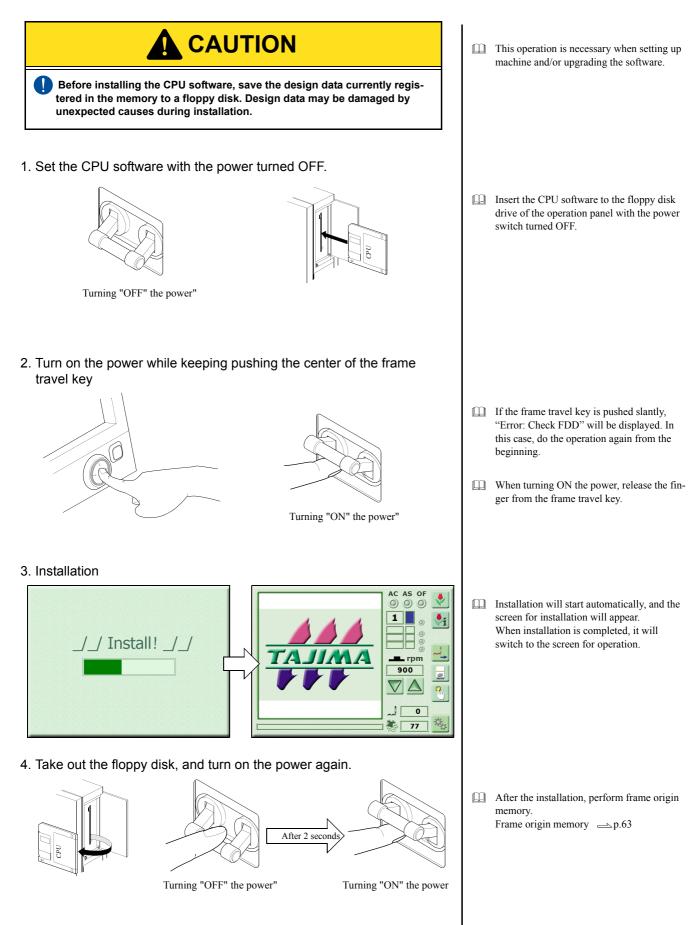


Press the button to eject the disk.



- FDD (Floppy Disk Drive) is the abbreviation of floppy disk drive.
- □ Formatting → p.57

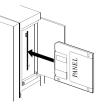
5. CPU SOFTWARE INSTALLATION



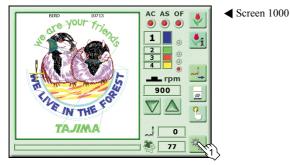
6. PANEL SOFTWARE INSTALLATION

Before installing the PANEL software, save the design data currently registered in the memory to a floppy disk. Design data may be damaged by unexpected causes during installation.

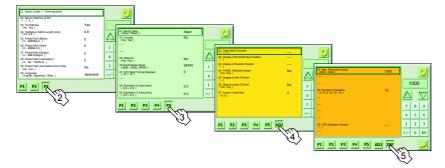
1. Insert the PANEL software to the FDD



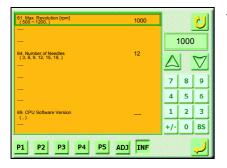
2. Switch to the screen 3000



3. Display switching of the screen 3000



4. Take note of setting value



Screen 3000

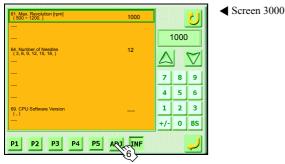
This operation is necessary when setting up machine and/or upgrading the software. Start the operation from a state of turning "ON" the power.

Press each of P3, P5, and ADJ two times, and then press INF.

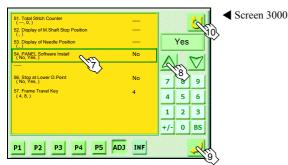
Take note of the contents of the following parameter setting.
 61. Max. Revolution [rpm]
 64. Number of Needles

It will become necessary to set parameters as described above when confirming them after installation of the software.

5. Switching to the ADJ screen



6. Install the PANEL software

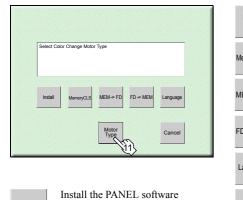


CAUTION

During reading of floppy disk, the operation panel will be in a state as if it stopped for a few seconds. Do not operate the panel in this moment. Otherwise, installation may not be performed normally.

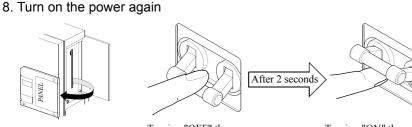
7. PANEL software installation

Install



Motor Type	Selection of color change motor (Type 1/Type 2)
emoryCLS	Delete all memories
EM→ FD	Backup memory contents to floppy disk
D→ MEM	Restore backup memory of floppy disk
.anguage	Switching of language display

Cancel the installation



Cancel

- Turning "OFF" the power
- Turning "ON" the power

Select PANEL software installation, and perform registration with "Yes". Pressing "Return" will abort the screen after a few seconds and the screen for installation will appear.

COLOR CHANGE MOTOR

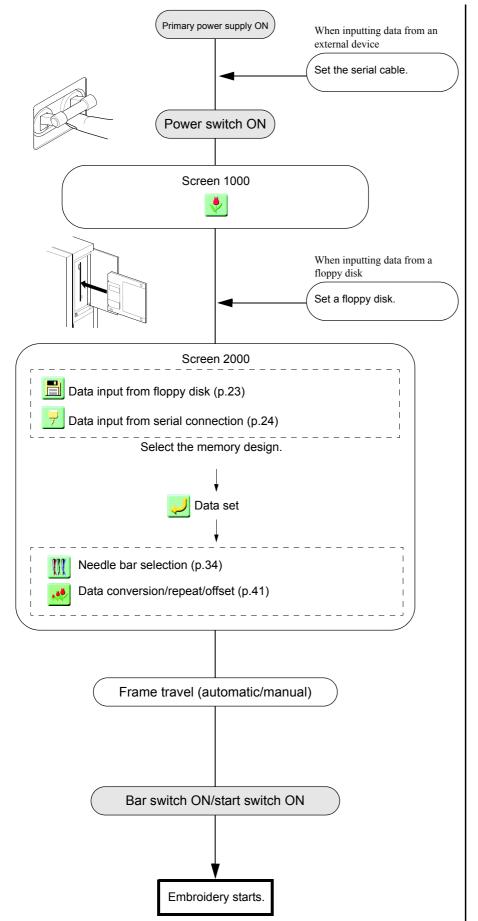




Motor shaft length of Type1 is different from that of Type 2.

- Deressing "Motor Type" will cause "Type 1/ Type 2" to be switched and "Install" button to be displayed. After selecting motor type, press the "Install" button to start installation.
- When performing backup of data and/or switching language display, consult the distributor.
- When cancel was made, turn on the power again.
- When installation is completed, "system Reboot!!" will appear on the screen. Take out the floppy disk, and turn on the power again.
- Check the following parameters. 61. Max. Revolution [rpm] 64. Number of Needles

7. OPERATION FLOW

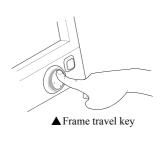




▲ Screen 1000



▲ Screen 2000

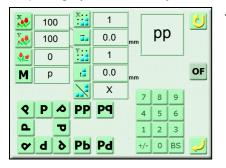




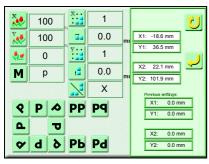
▲ Start switch

8. VALUE INPUT

1. Inputting by numerical keys



2. Value input by frame travel



9. INPUT OF CHARACTERS

Cursor

BS

8 9

OP

Cp Lg

L -

TAJIMA 🖌

E R T Y U I

B N M

▲ Screen A000

0 1 2 3 4 5 6 7

A S D F G H J K

QW

ZXCV

Screen 6000
 7 8
 4 5
 1 2
 +/- 0
 Numerical keys ►

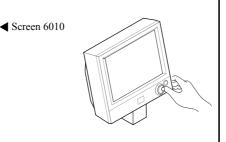
Previous state

-Switching of language

- Switching of capital/small letters

Deletion

Decision



9

6

3

BS

Select the input column, and input the value with numerical keys.
 To make correction, press "BS" to delete the value, and input value again.

Press this icon to register all input values.

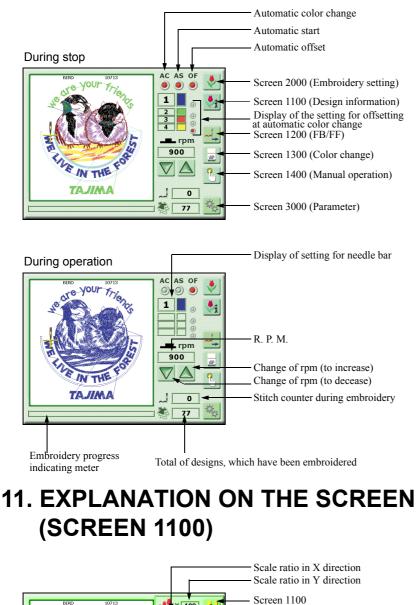
When moving the embroidery frame to a free setting position by the frame travel keys or the jog remote-controller, the position will be displayed with coordinate values.

Treat it the same as the keyboard.



It is not possible to input space.

10. EXPLANATION ON THE SCREEN (SCREEN 1000)



Y 100 2 Rotating angle X 100 👷 🚺 m P-Mirror image reversion The number of repeats in Y direction Y 1 Pd PP-Repeating direction (1. The number of repeats in X direction 57.0 +/-X and +/-Y size from the origin - 56.8 TAJIMA - 7.2 95.2 Colors 10 The number of design steps

- When setting is made on AC, AS, and/or OF, it will be displayed in red.
- The position where offsetting at automatic color change is set will be displayed in red.
- The position where offsetting at automatic color change is set will be displayed in red.

 R. P. M. It display the maximum r.p.m. during stop, and it is not possible to change the rotating speed.
 It displays the r.p.m. during operation. Pressing the icon for changing r.p.m. will cause

the r.p.m. to be changed.

☐ It display the information of design of which data was converted. Data conversion → p.35

12. INSPECTION BEFORE STARTING EMBROIDERY

WARNING

When performing inspection before starting embroidery, turn OFF the power. You may be caught by the machine or sticking needle may cause severe injury.

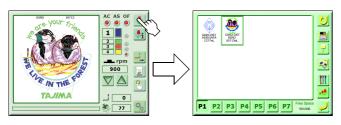
Inspecting item	Condition	Action to take	
Cover	Cover(s) depart from the machine.	Attach the cover to the machine.	
Thread	Thread(s) depart from the original position.	Set thread(s).	
	Thread(s) are broken.		
Needle	Needle(s) are bent. Change the needle(s).		
	Needle(s) are broken.		
Rail on rotary hook	Appropriate quantity of oil is not supplied to the rail section.	Supply oil	

CHAPTER 4 **DATA SET**

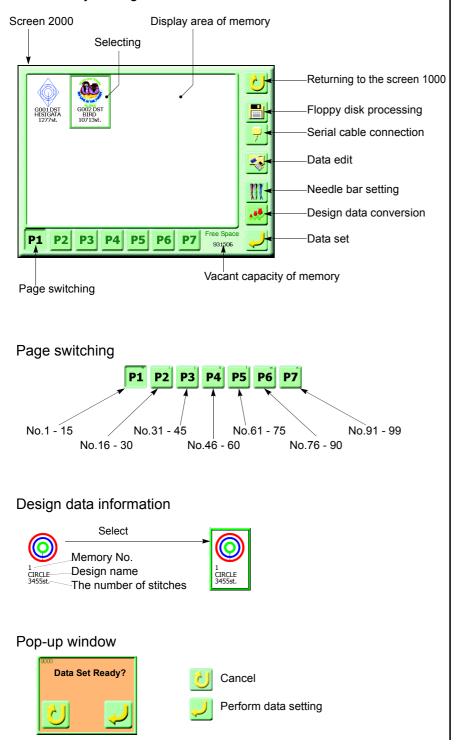


1. EXPLANATION ON THE SCREEN (SCREEN 2000)

<How to call the screen>



Embroidery setting screen

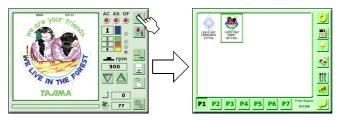


- When there is no design data in the memory, icons of "data edit, needle bar setting, design data conversion, data set, page switching" will not be displayed.
- Vacant capacity of the memory displays the number of remaining stitches of design data that can be registered in the memory.
 When the memory has no vacant capacity, the icons that enable data input of "floppy disk processing, serial cable connection" will disappear.

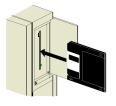
- Up to 15 designs are displayed at the display area of memory designs, and 16 and after designs are displayed at the next page.
 16 and after designs are stored at "P2". Page switching icons will be added by the number of designs stored in memory.
 It is possible to register up to 99 designs in the memory.
- The selected design will be surrounded by a frame.

2. DATA INPUT FROM FLOPPY DISK

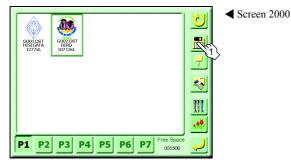
<How to call the screen>



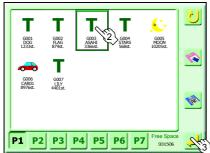
1. Insert the floppy disk.



2. Reading the floppy disk



3. Selection of design and input



- 4. Completion of input

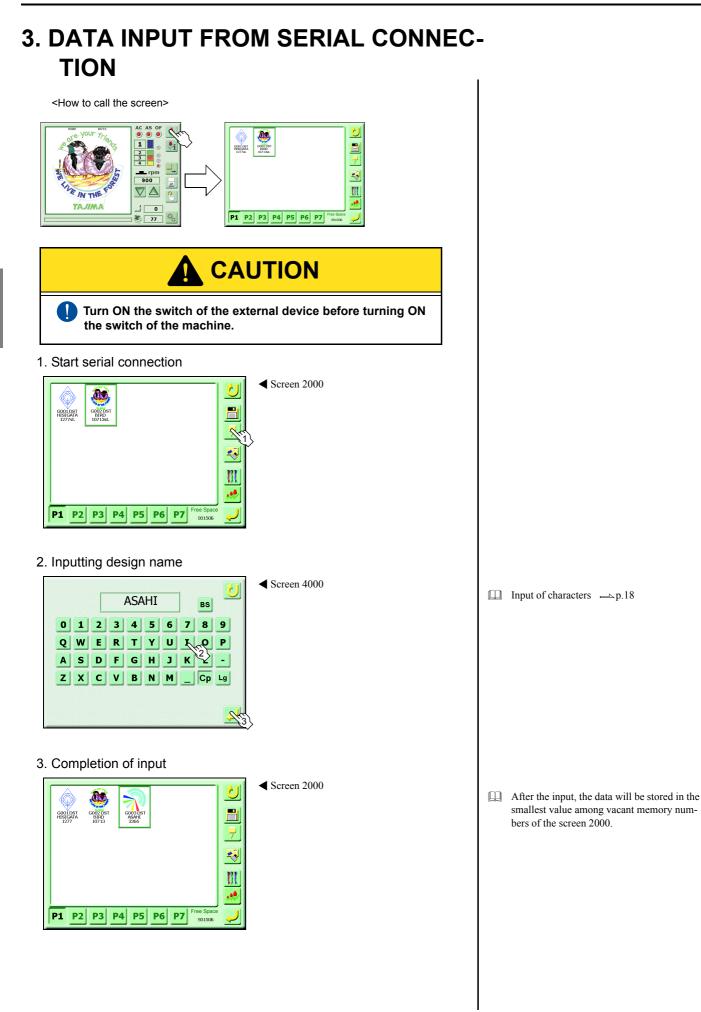


Screen 2000

◀ Screen 4000

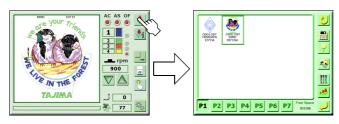
Pressing the design being selected once more will cause the design to be displayed.

After the input, the data will be stored in the smallest value among vacant memory numbers of the screen 2000.

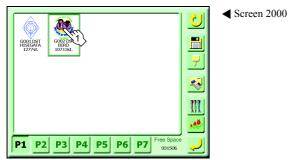


4. DATA SET

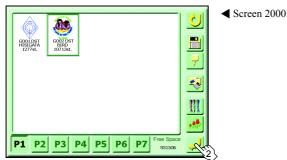
<How to call the screen>



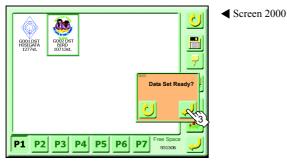
1. Selection of design



2. Data set



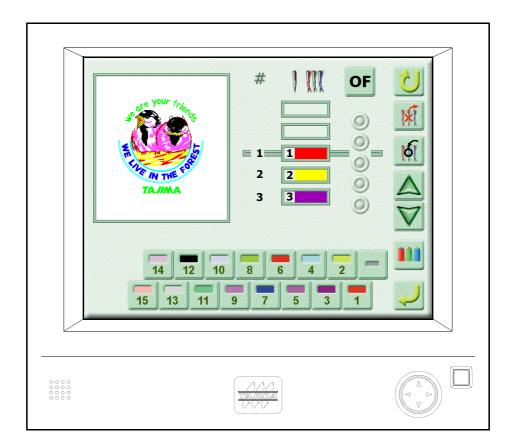
3. Confirm



- When setting embroidery conditions, press needle bar setting and data conversion to make setting.
 Needle bar setting → p.28
 Data conversion → p.35
- Setting for automatic offset position must be performed after data set.
 Automatic offset ____p.42

26 CHAPTER 4 DATA SET

CHAPTER 5 EMBROIDERY SETTING



Design display

TAJIMA

15 13 11 9 7 5 3 1

#

2

3 12

4 2

10 8 6

14 12

Needle bar number key

1 11

4

2

1 7

OF

0

0

0

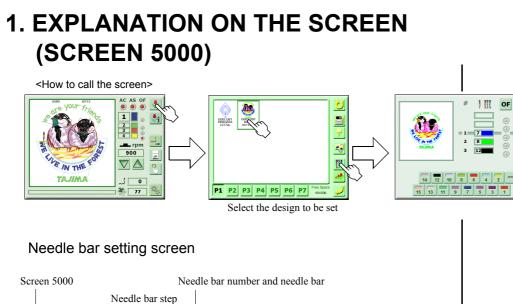
0

K

6

V

Repeat setting Offsetting at automatic color change is set



Offsetting at automatic color

To return to the screen 2000

Deletion of needle bar step

Insertion of needle bar step

Selection of needle bar step

Setting of needle bar color

change

Register

Changing the needle bar will also cause color of design display to be changed.

1

6

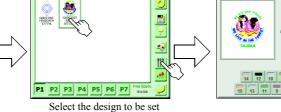
Registering the setting for needle bars will cause the screen to return to the screen 2000.

Selecting position of needle bar step

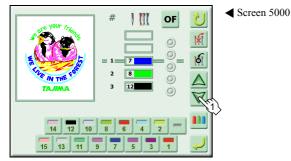
2. CHANGE OF NEEDLE BAR

<How to call the screen> AS OF 1 . 3 900 2 $\nabla \Delta$ IN THE

TAJIMA



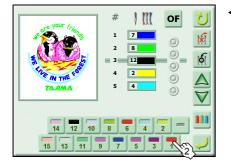
1. Select the needle bar step



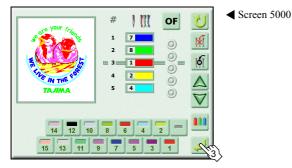
→ 0 巻 77

\$\$. \$

2. Select the target needle bar number to be changed



3. Register



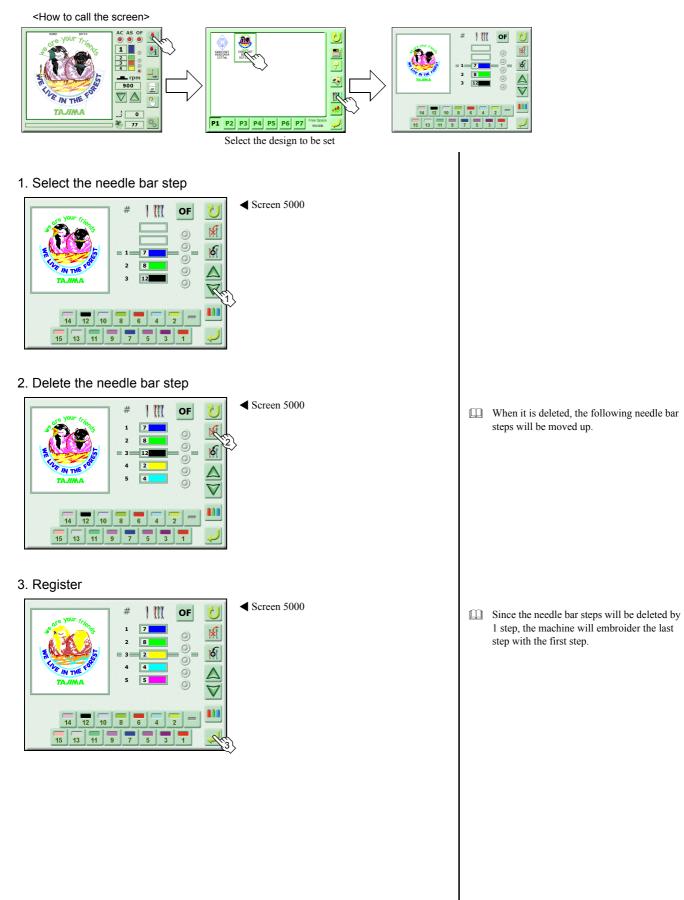
◀ Screen 5000

111 OF 1 6 4 12 10 8 6 15 13 11 9 7 5 3

> Selecting a needle bar step will cause the design display of the step being selected will blink.

- It is also possible to change other needle bars as the same way.
- Selecting the target needle bar number will also change color of design display.

3. DELETION OF NEEDLE BAR STEP



1111 OF

1

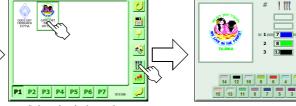
6

1

4. INSERTION OF NEEDLE BAR STEP

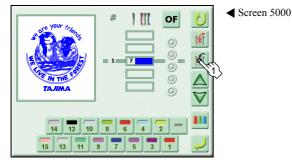




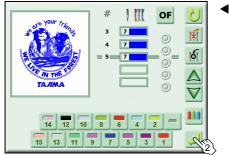


Select the design to be set

1. Insert the needle bar step



2. Register

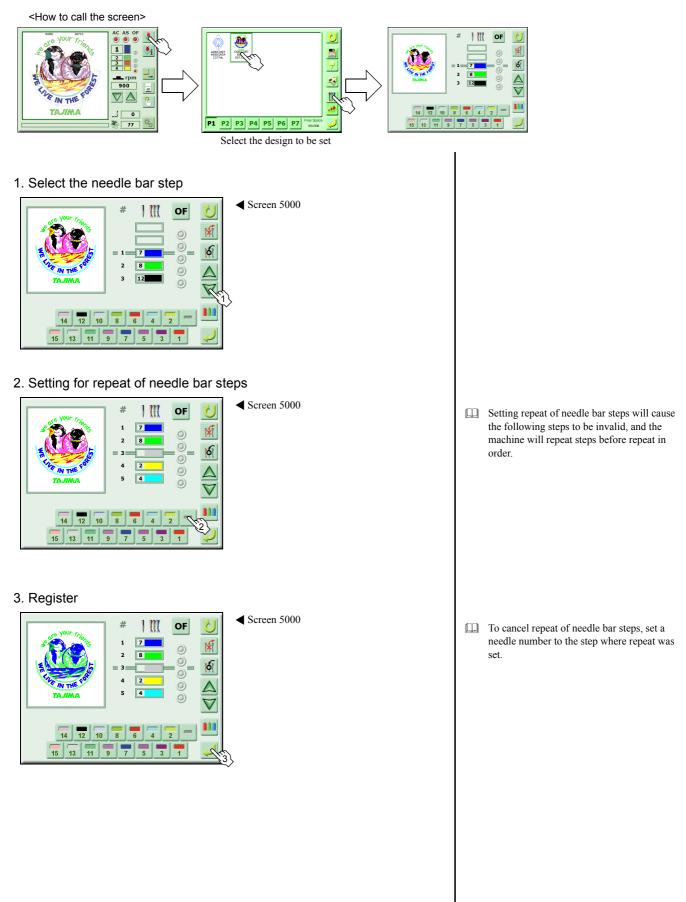


✓ Screen 5000

- Insertion will copy the needle bar step being selected to insert.
- It is possible to perform insertion up to the number of steps set in the stitch data.

Change the inserted needle bar step to the needle number you desire. Change of needle bar ____p.29

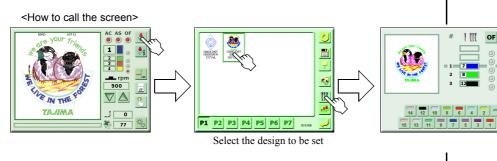
5. REPEAT OF NEEDLE BAR SETTING



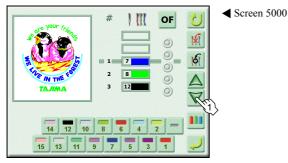
1

6

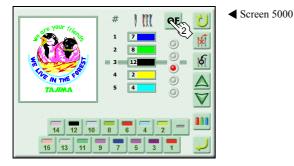
6. OFFSETTING AT AUTOMATIC COLOR CHANGE



1. Select the needle bar step



2. Set offsetting at automatic color change



3. Register



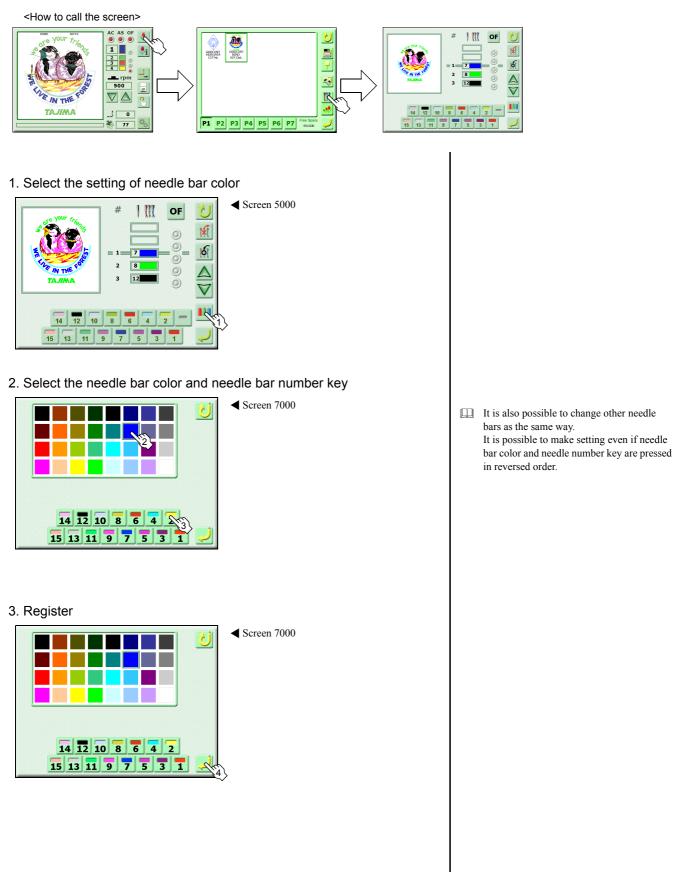
◀ Screen 5000

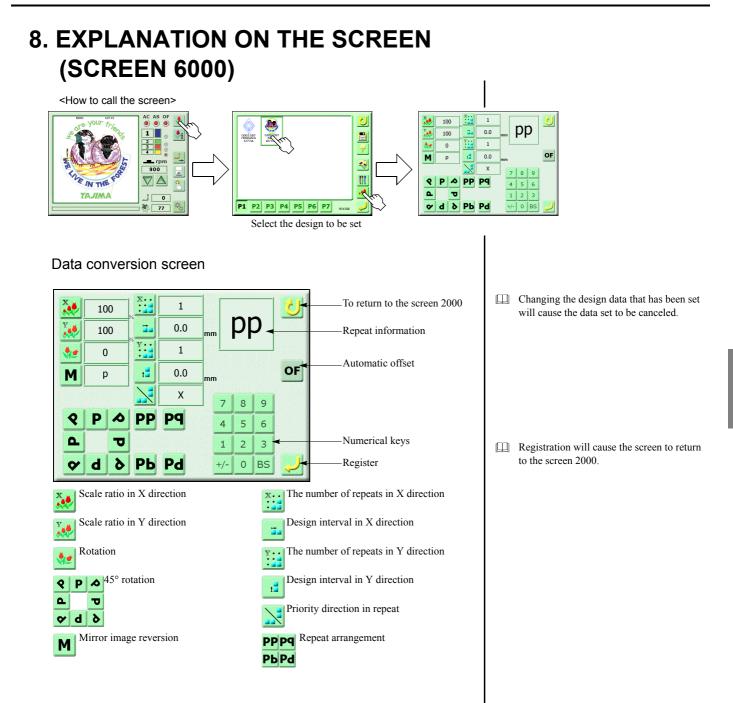
Offsetting at automatic color change is a setting that makes the frame move to the position set by the automatic offset when the machine performs color change.
 When automatic offset is not registered, the frame will not move.
 Automatic offset ___p.41

- Setting offsetting at automatic color change will cause the frame to move to the setting position of automatic offset when the set step ends.
- It is also possible to set other needle steps as the same way.

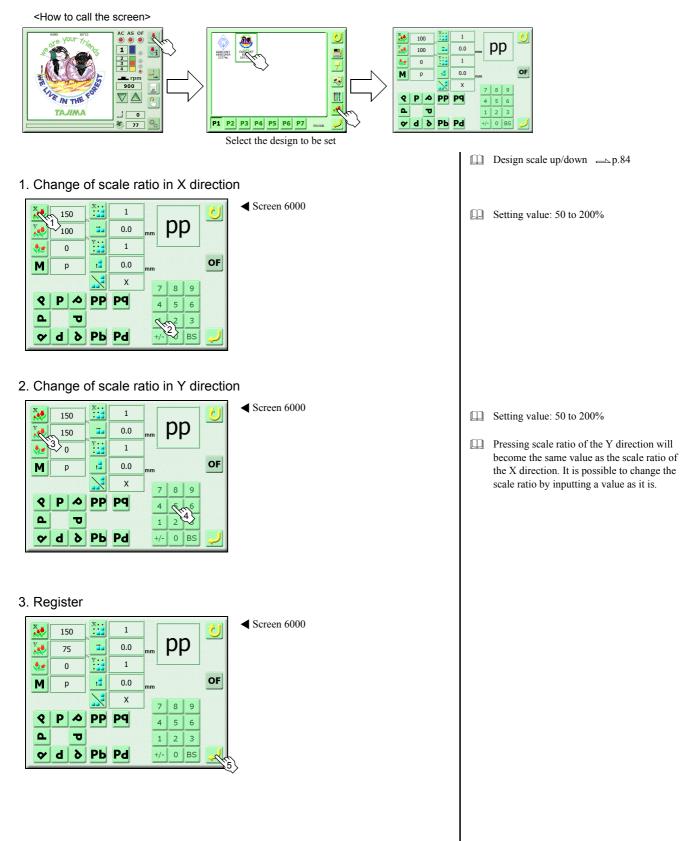
To cancel offsetting at automatic color change, select the step being selected, and then press "OF".

7. NEEDLE BAR COLOR





9. DESIGN SCALE UP/DOWN



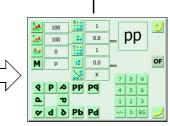
10. ROTATION/MIRROR IMAGE REVER-SION

<How to call the screen>



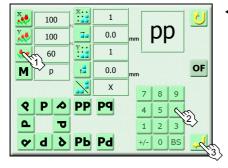


Select the design to be set

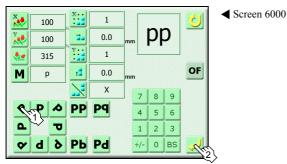


Rotation by input of value

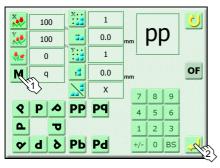
✓ Screen 6000



Rotation by 45° unit



Mirror image (reversion)



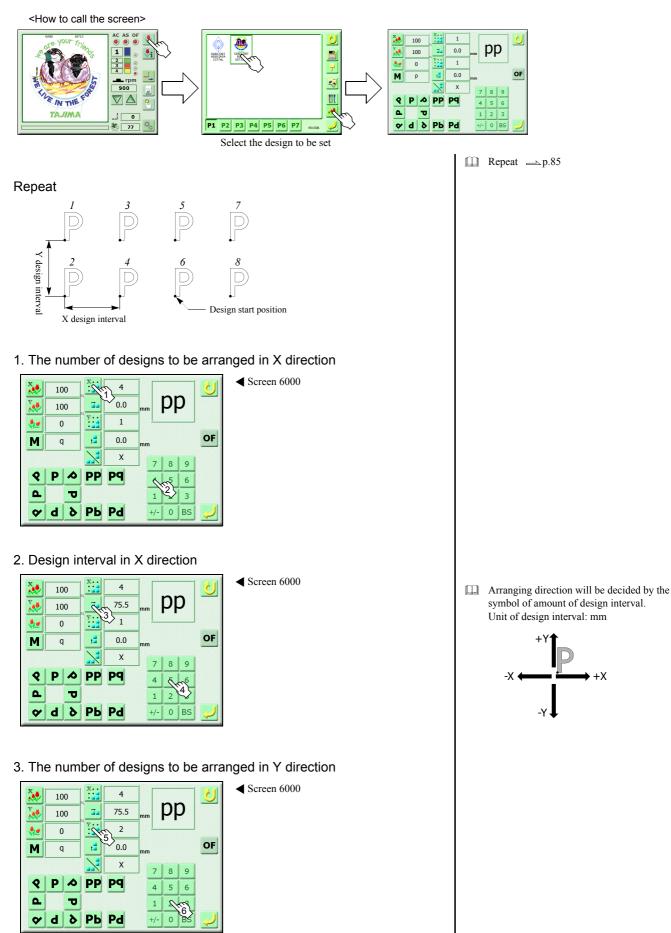
✓ Screen 6000

Rotation/mirror image reversion ____p.84

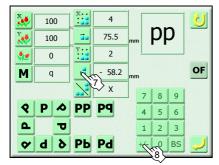
 \square It is possible to input value by 1° unit.

Every pressing "M" will switch direction.

11. REPEAT

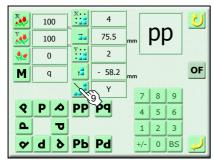


4. Design interval in Y direction

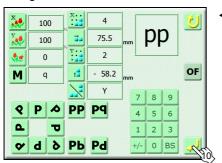


◀ Screen 6000

5. Priority direction



6. Register



◀ Screen 6000

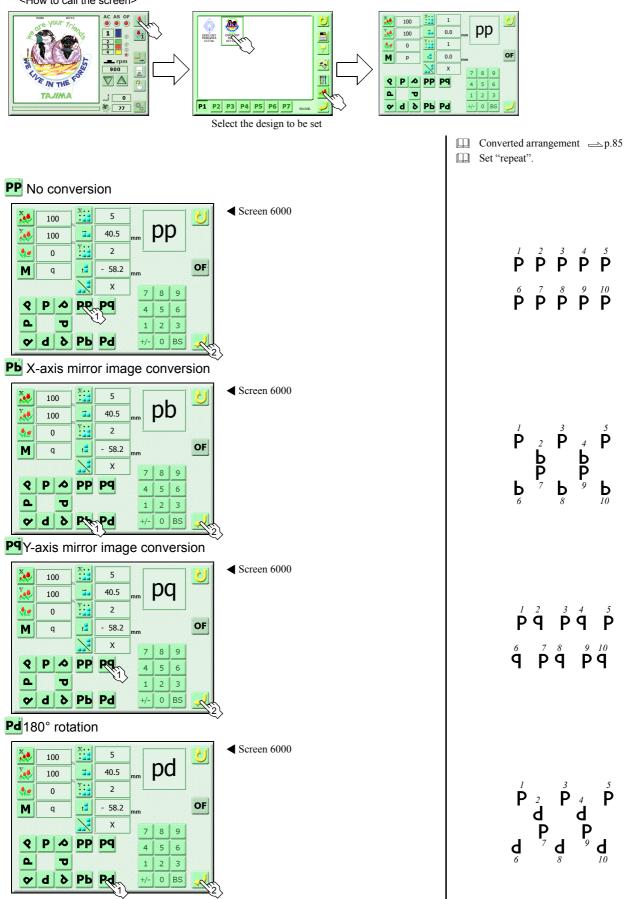
◀ Screen 6000

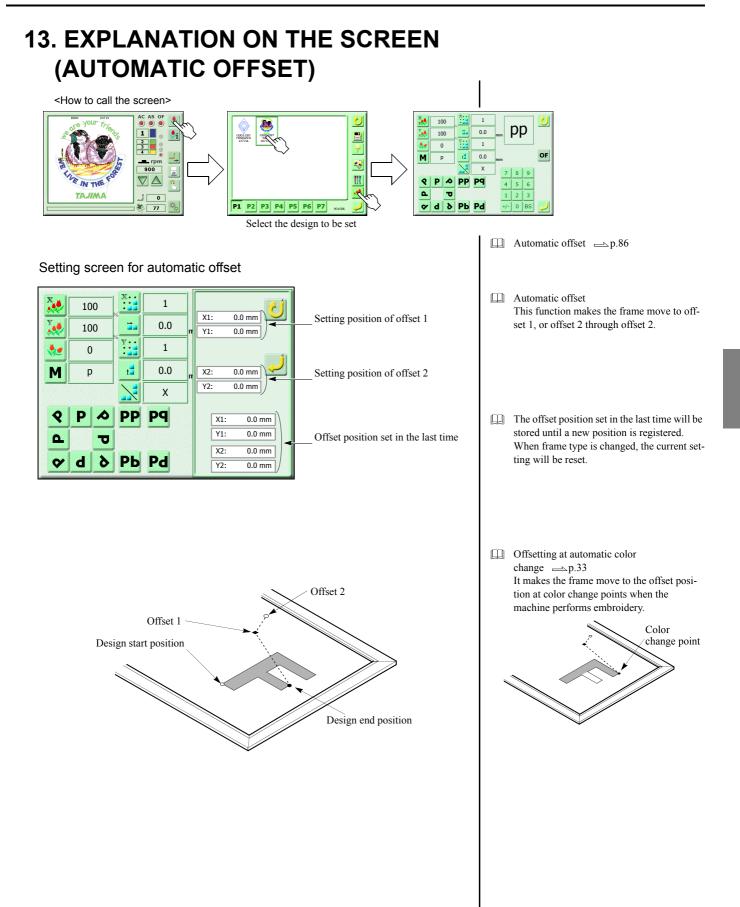
 \square The direction of priority (X/Y) will be switched every time the icon is pressed.

X priority \mathbf{P}^{T}_{6} \mathbf{P}^{T}_{7} \mathbf{P}^{8}_{8} \mathbf{P} \mathbf{P} \mathbf{P} \mathbf{P} P 9 10 P P Y priority $\begin{array}{cccc} I & 3 & 5 & 7 & 9 \\ P & P & P & P & P \\ 2 & 4 & 6 & 8 & 10 \\ P & P & P & P & P \end{array}$

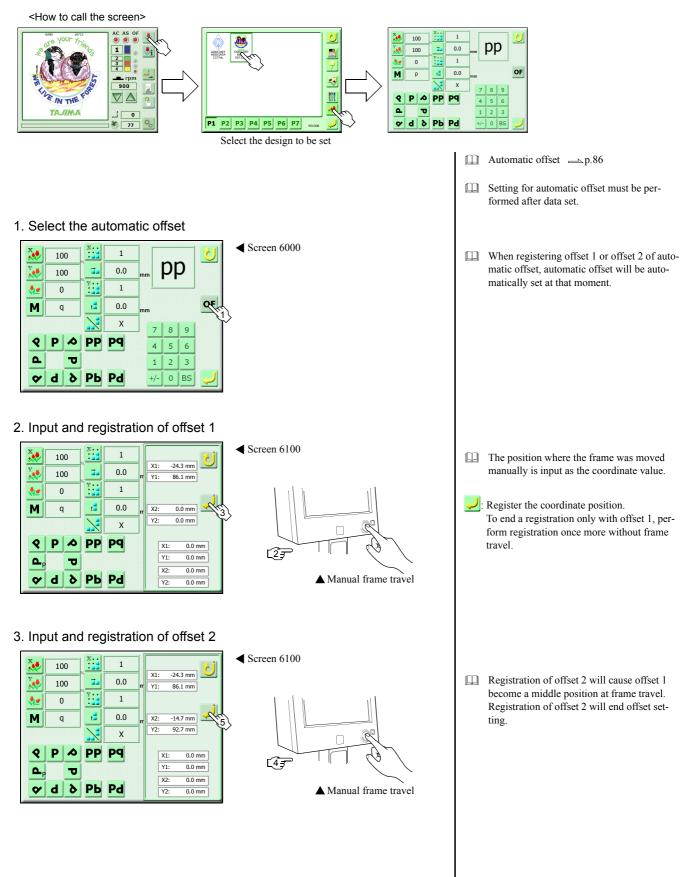
12. REPEAT (CONVERTED ARRANGE-MENT)

<How to call the screen>





14. AUTOMATIC OFFSET



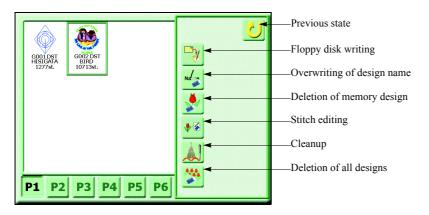
CHAPTER 6 DESIGN DATA MANAGEMENT



1. EXPLANATION ON THE SCREEN (SCREEN 2200)



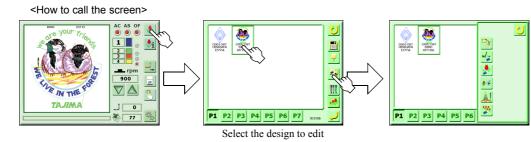
Design data management screen



Editing the design data that has been set, the data set will be canceled.

Input of characters _____p.18

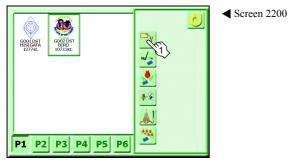
2. FLOPPY DISK WRITING



1. Insert the floppy disk.



2. Select the floppy disk writing

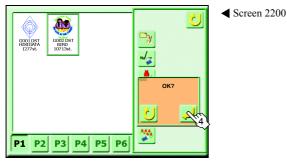


3. Input a file name

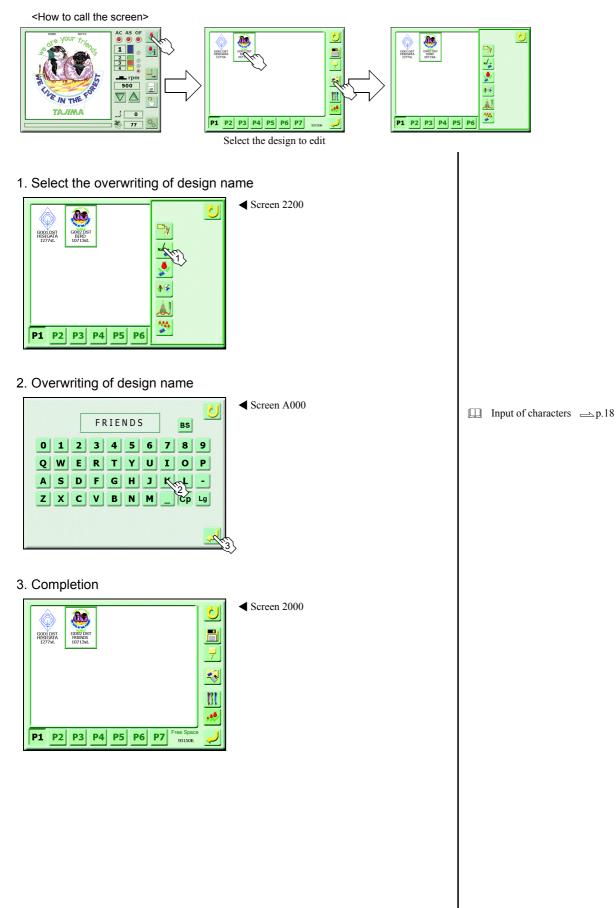


◀ Screen A000

4. Confirm

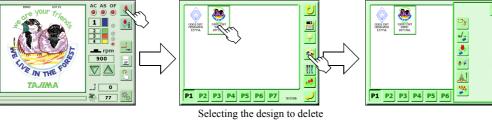


3. OVERWRITING OF DESIGN NAME

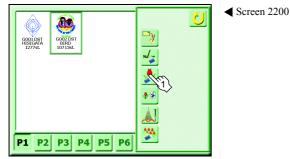


4. DELETION OF MEMORY DESIGN

<How to call the screen>



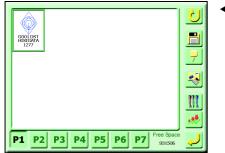
1. Select deletion of design



2. Confirm



3. Completion

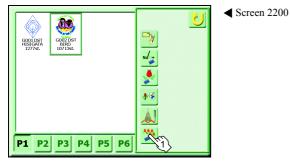


Screen 2000

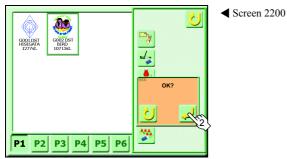
5. DELETION OF ALL DESIGNS



1. Select the deletion of all designs



2. Confirm



3. Completion



Screen 2000

6. CLEANUP

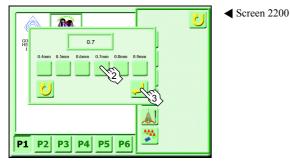


Screen 2200

1. Select the cleanup



2. Cleanup processing



3. Completion

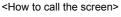


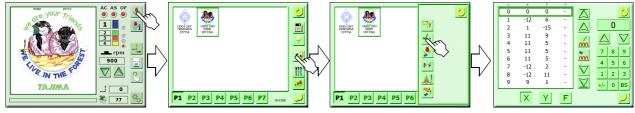
◀ Screen 2000

Cleanup is a function that makes the preceding and the succeeding stitches absorb a fine stitch to be removed to prevent thread coming off or thread breakage.

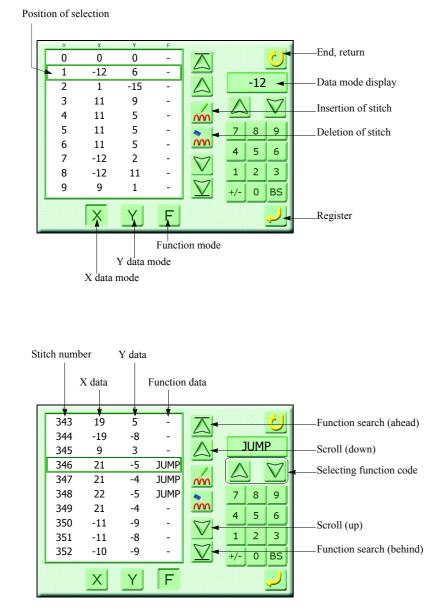
Applicable cleanup stitch lengths are 0.4 to 0.9 mm. As this function searches a corresponding stitch and makes the preceding and the succeeding stitches absorb it, the design will be somehow changed.

7. EXPLANATION ON THE SCREEN (SCREEN 8000)





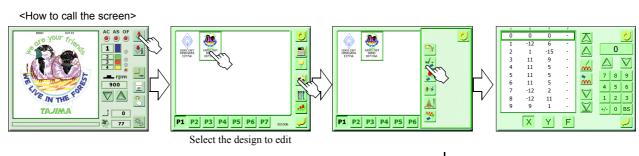
Stitch editing screen



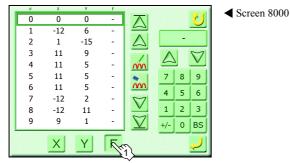
- Stitch data Unit of X, Y stitch data is 0.1 mm. Each stitch data is displayed with relative coordinates assuming the coordinates prior to one stitch are (0, 0).
- Data mode display Selecting either X or Y function mode will display data that exists at the mode of the selecting position.

- Function search
 When performing searching after selecting the function mode and the function code, the machine will search data existing near forward or backward of the function code to display.
- Scroll
 Data by 10 stitches of forward/backward will be displayed.

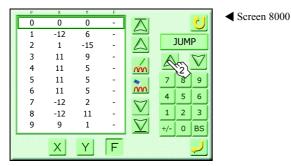
8. FUNCTION SEARCH



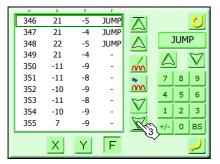
1. Select the function mode



2. Select the function code



3. Function search



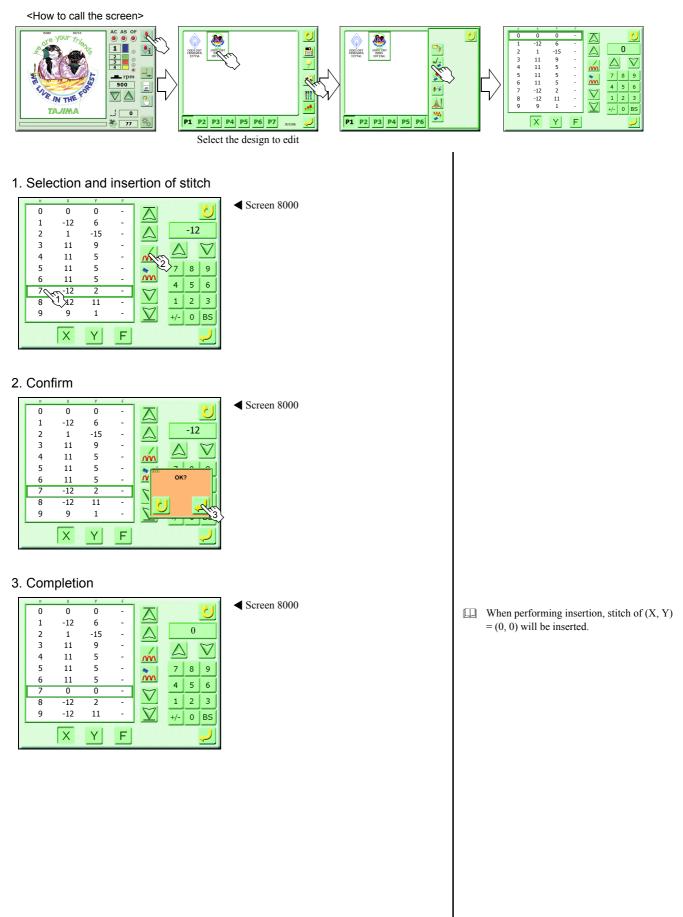
Screen 8000

E Function code

END	End
SEQ	Sequin
ATH	Automatic thread trimming (ATH)
LOW	Low speed revolution
HIGH	High speed revolution
JUMP	Jump
STOP	Stop (color change)
-	Stitch

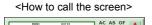
It is possible to search other function codes with the same operation.

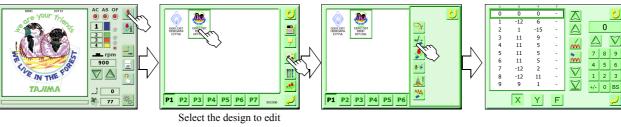
9. INSERTION OF STITCH



 ∇

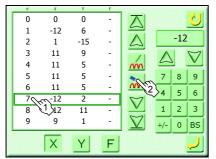
10. DELETION OF STITCH

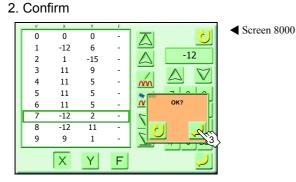




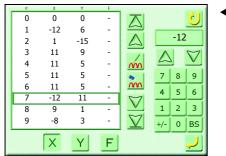
◀ Screen 8000

1. Selection and deletion of stitch





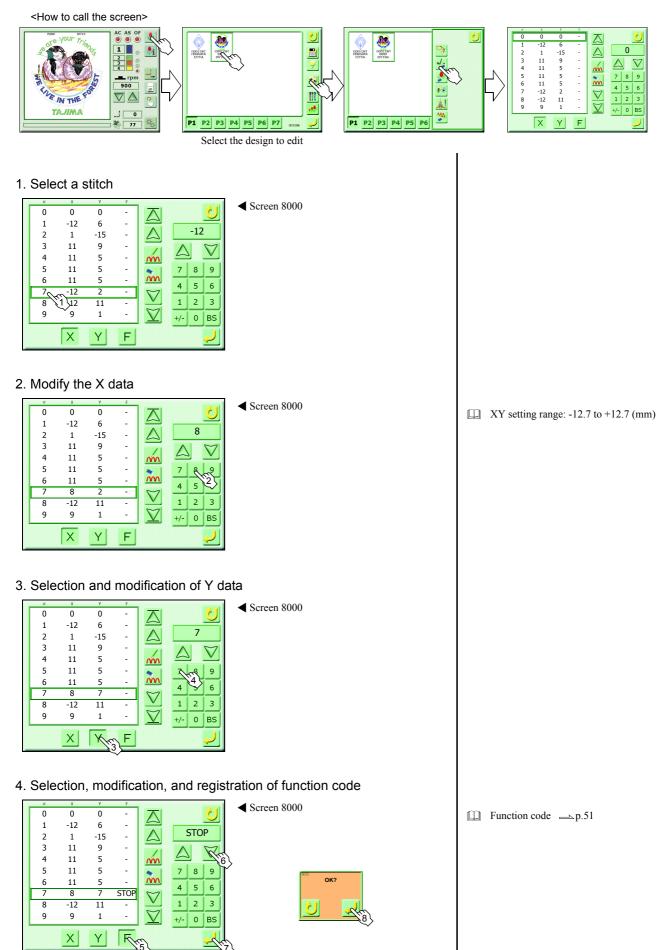
3. Completion



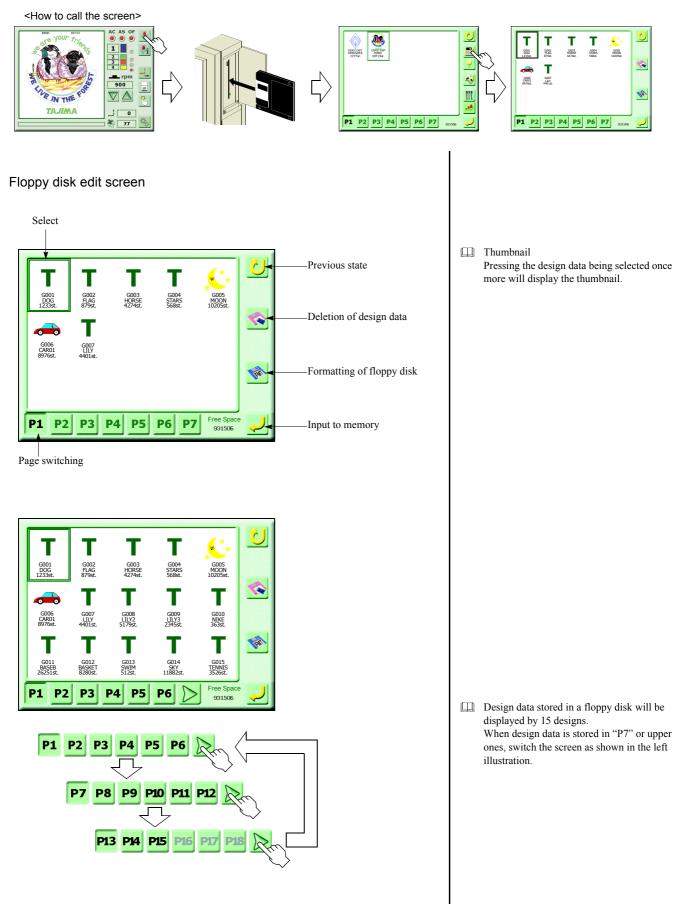
◀ Screen 8000

When performing deletion, the stitch being selected and the following ones will be moved up.

11. MODIFICATION OF STITCH DATA



12. EXPLANATION ON THE SCREEN (SCREEN 3000)



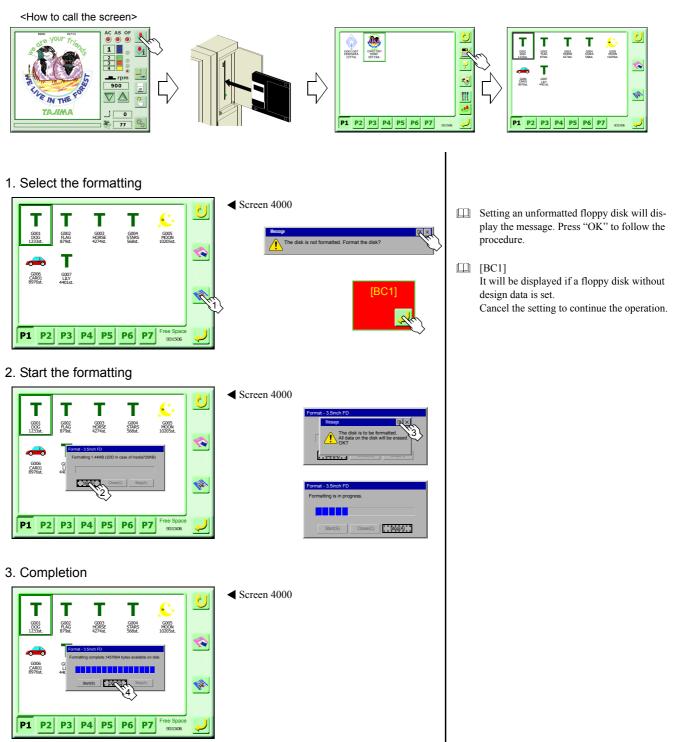
13. DELETION OF DESIGN DATA IN FLOPPY DISK

<How to call the screen> AC AS OF CODLDST HISTIGATA 127754 U G003 HORSE 4274st. Т G005 MOON 10205# Т T 1 . i R 6002 FLAG 879xt. G004 STARS S68st 6001 DOG Т ... ~i_ GE06 CAR01 8976st. 6007 LULY 4401st 900 2 $\nabla \Delta$ IN THE TAJIMA 10 P1 P2 P3 P4 P5 P6 P7 P1 P2 P3 P4 P5 P6 P7 1. Select the design data ◀ Screen 4000 0 Т Т Т بي ا Τ G004 STARS G005 MOON 10205st. G001 DOG 1233st. G002 FLAG 879st. G003 HORS Т G006 CAR01 8976st. G007 LILY 4401st PH P1 P2 P3 P4 P5 P6 P7 Free Space ~ 2. Delete the design data ◀ Screen 4000 0 Т Т <u>(*</u> Т Т G002 FLAG 879st. G003 HORSE G004 STARS G005 MOON 10205et G001 DOG 1233st. < Т 0 OK? G006 CAR01 8976st G007 LILY 4401st 2 P1 P2 P3 P4 P5 P6 P7 Free Spac 3. Result ◀ Screen 4000 2 Т Т Т ~~ G005 MOON 10205st. G005 MOON 10205et G001 DOG 1233st. G002 FLAG 879st. G004 STARS 568st Т G007 LILY 4401st Far Free Spac 931506 P1 P2 P3 P4 P5 P6 P7 \checkmark

0

-

14. FORMATTING OF FLOPPY DISK



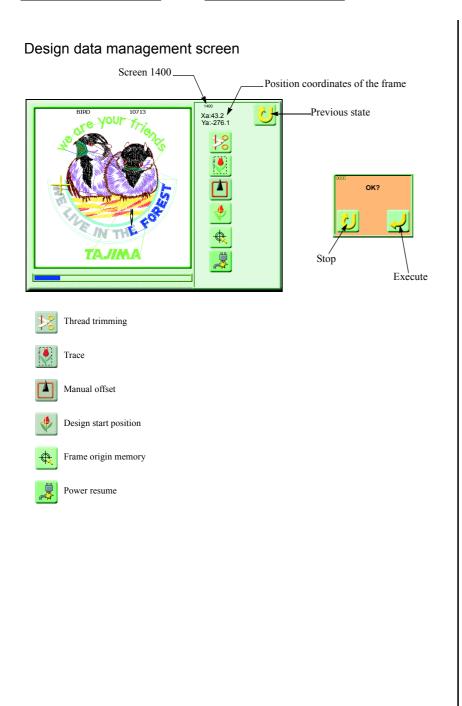
CHAPTER 7 MANUAL OPERATION



1. EXPLANATION ON THE SCREEN (SCREEN 1400)

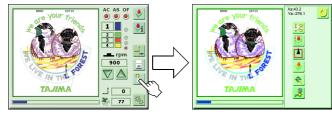
<How to call the screen>





2. THREAD TRIMMING/TRACE

<How to call the screen>



WARNING

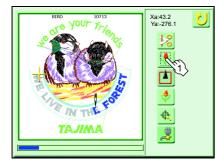
When performing this operation, do not put your hands under the needle or on the machine table. If your hands are under the needle or on the machine table, you may be injured by the needle or the moving frame.

Thread trimming





Trace



◀ Screen 1400

◀ Screen 1400



Trace ____p.88

3. MANUAL OFFSET/DESIGN START POSITION

<How to call the screen>



WARNING

When performing this operation, do not put your hands under the needle or on the machine table. If your hands are under the needle or on the machine table, you may be injured by the needle or the moving frame.

Manual offset

 \mathbf{O}





Design start position



Screen 1400

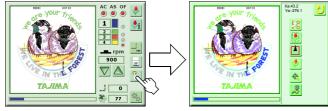


 □ Return the frame that was moved to the original position.
 Manual offset → p.86

 \square The frame moves to the design start position.

4. FRAME ORIGIN MEMORY

<How to call the screen>



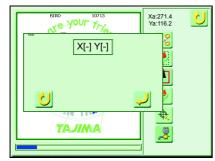
WARNING

When performing this operation, do not put your hands under the needle or on the machine table. If your hands are under the needle or on the machine table, you may be injured by the needle or the moving frame.

1. Select frame origin memory



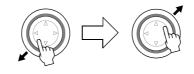
2. Search the origin



◀ Screen 1400

◀ Screen 1400

Frame travel key



Move the frame to the front left with the frame travel key. After moving the frame to the position until it does not move, move the frame to the rear right direction.

Move the frame with the frame travel key to make the machine memorize the origin of

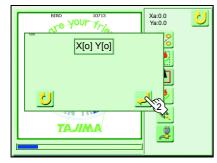
Perform this operation after the software was installed or when the frame was moved dur-

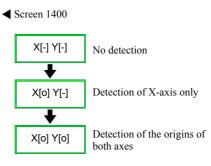
the embroidery frame.

ing turning off the power.

Jog remote-controller is not available for use.

3. Memorize the origin





- When the position of the origin is searched, [-] will switch to [o]. When the origins of both axes are searched, make the machine memorize the positions.
- When the machine memorizes the origin, the frame will return to the original position.

5. POWER RESUME

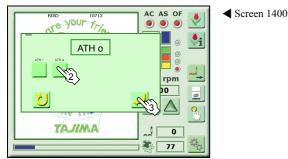


When performing this operation, do not put your hands under the needle or on the machine table. If your hands are under the needle or on the machine table, you may be injured by the needle or the moving frame.

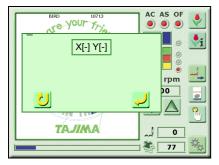
1. Machine stop code



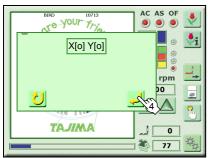
2. Selecting the thread trimming



3. Search the origin

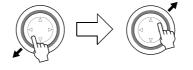


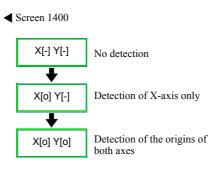
4. Memorize the origin



Screen 1400

Frame travel key





In case of power shut off by power failure, turn "OFF" the power and then turn it "ON" to start operation.

Power resume function moves the frame to the position where the power was shut off during embroidery to prevent displacement of design.

Automatic thread trimming (ATH)

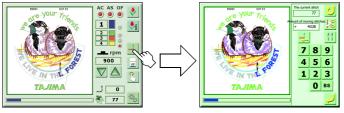
ATH -	Not to perform thread trimming
ATH o	To perform thread trimming

□ Move the frame to the front left with the frame travel key. After moving the frame to the position until it does not move, move the frame to the rear right direction.

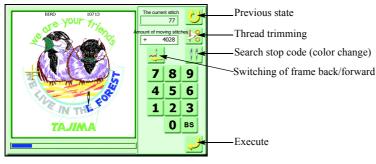
- When the position of the origin is searched,
 [-] will switch to [o]. When the origins of both axes are searched, make the machine memorize the positions.
- When the machine memorizes the origin, the frame will return to the position where the power was shut off.

6. FRAME BACK/FORWARD

<How to call the screen>



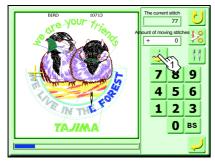
Explanation on the screen (screen 1200)





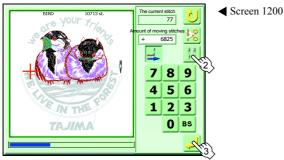
When performing this operation, do not put your hands, etc. on the machine table. Moving embroidery frame will cause you injured.

1. Select the frame back/forward



◀ Screen 1200

2. Input and execution of amount of moving stitches



- Frame back breaks the embroidery and causes only the frame to move to the direction where stitch(es) return.
 Frame forward breaks the embroidery and causes only the frame to move to the direction where stitch(es) advance.
- +/- of amount of moving stitches changes to frame back "-", or frame forward "+".



Every pressing switches frame back/forward.

Perform thread trimming if necessary.

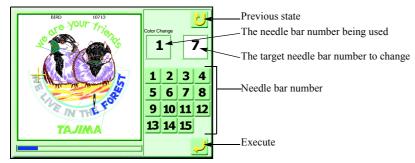
- Every pressing of stop code searching will search the next stop code. It is also possible to input the number of stitches by numerical keys.
- Execution will perform frame back/forward by the specified stitches.

7. COLOR CHANGE (SCREEN 1300)

<How to call the screen>



Explanation on the screen



1. Select the needle bar to change



Screen 1200

2. Execute



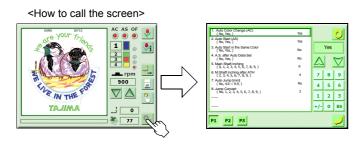
Screen 1200

Color change only changes needle bars that you desire to change without changing needle bar setting at embroidering.

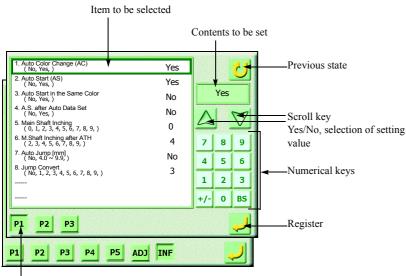
CHAPTER 8 PARAMETER SETTING

2. Auto Start in the Same Color (No, Yes,) Yes 3. Auto Start in the Same Color (No, Yes,) No 4. A.S. after Auto Data Set (No, Yes,) No 5. Main Shaft Inching (0, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 0 6. M.Shaft Inching after ATH (2, 3, 4, 5, 6, 7, 8, 9,) 0 7. Auto Jump [mm1 (No, 40 ~ 9.9) No 8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 3 1 +/- P1 P2 P3	1. Auto Color Change (AC) (No, Yes,) 2. Auto Start (AS)	Yes
(No, Yes,) No 4. A.S. after Auto Data Set (No, Yes,) No 5. Main Shaft Inching (0, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 0 6. M.Shaft Inching after ATH (2, 3, 4, 5, 6, 7, 8, 9,) 4 7. Auto Jump [mm] (No, 4, 0 ~ 9, 9) No 8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 3 1 +/- +/-	(No, Yes,)	
(No, Yes,) No 5. Main Shaft Inching (0, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 0 6. M.Shaft Inching after ATH (2, 3, 4, 5, 6, 7, 8, 9,) 4 7. Auto Jump [mm] (No, 40~9.9) No 8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 3 1 +/- +/-	3. Auto Start in the Same Color (No, Yes,)	No
6. M.Shaft Inching after ATH 4 7 8 9 7. Auto Jump [mm] No 8 4 5 6 8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 3 1 2 3 +/- 0 BS		No
6. M.Shaft Inching after ATH 4 7 8 9 7. Auto Jump [mm] No 8 4 5 6 8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 3 1 2 3 +/- 0 BS	5. Main Shaft Inching (0, 1, 2, 3, 4, 5, 6, 7, 8, 9,)	
7. Auto Jump [mm] (No, 4.0 ~ 9.9) No 8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 3 1 +/- +/-		4 7 8 9
8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,) +/- 0 BS		No
<u>1 2 3</u> +/- 0 BS		
		1 2 3
P1 P2 P3		+/- 0 BS
	P1 P2 P3	

EXPLANATION ON THE SCREEN



Parameter setting screen



Page switching

- Setting items of parameter may not be displayed depending on machine specification. Setting items of parameter may be different from this manual due to research and development.
- It is possible to input all setting values using the scroll keys.

 Input of setting value using numerical keys When inputting values only, it is also possible to input them using the numerical keys. To perform inputting, delete the value by the "BS key" and then input a value. It is not possible to register values outside the setting range.

Page switching Pressing "P3" twice will display "P4, P5". Pressing "P5" twice will "ADJ". pressing "ADJ" twice will display "INF".



When needle bar step switches, automatic color change will be performed.

ļ		
	Yes	To perform automatic color change automatically "AC" lamp of the screen 1000 lights in red
	No	Not to perform automatic color change automatically

When needle bar step changes, automatic start will be performed.

Ш

Yes	Automatic start is performed "AS" lamp of the screen 1000 lights in red
No	Automatic start is not performed

It is possible to make setting when "Yes" is set to "1. Auto Color Change".

Even if the same needle bar is selected before and after color change, automatic start will be performed.

τ.	m	
	ш	
	[D

Yes	Automatic start is performed
No	Automatic start is not performed

It is possible to make setting when "Yes" is set to "2. Auto Start".

It makes the machine start automatically to perform embroidery repeatedly at the same position after finishing the same design.

Ш		
	Yes	Automatic start is performed
	No	Automatic start is not performed

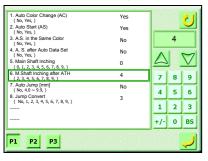
It is possible to make setting when "Yes" is set to "2. Auto Start".

It makes the machine perform inching when the machine starts.

(1) "0" does not perform inching after start of the machine.

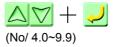
P1 P2 P3

6. M.Shaft Inching after ATH



7. Auto Jump [mm]

And the second			2000	Section and
1. Auto Color Change (AC) (No, Yes,)	Yes			115
2. Auto Start (AS) (No, Yes,)	Yes			
3. A.S. in the Same Color (No, Yes,)	No		No	
4. A. S. after Auto Data Set (No, Yes,)	No		1	
5. Main Shaft Inching (0, 1, 2, 3, 4, 5, 6, 7, 8, 9,)	0	1		$\overline{\nabla}$
 M.Shaft Inching after ATH (2, 3, 4, 5, 6, 7, 8, 9,) 	4	7	8	9
7. Auto Jump [mm] (No, 4.0 ~ 9.9,)	No	4	5	6
8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,)	3	<u> </u>	_	
		1	2	3
		+/-	0	BS
	CONTRACTOR OF	1.0	1997	
P1 P2 P3				



|+ 💛

(2~9)

8. Jump Convert

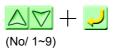
			and the	Service and
1. Auto Color Change (AC) (No, Yes,)	Yes			115
2. Auto Start (AS) (No, Yes,)	Yes			\leq
3. A.S. in the Same Color (No, Yes,)	No		3	
4. A. S. after Auto Data Set (No, Yes,)	No		1	M
5. Main Shaft Inching (0, 1, 2, 3, 4, 5, 6, 7, 8, 9,)	0	5		
 M.Shaft Inching after ATH (2, 3, 4, 5, 6, 7, 8, 9,) 	4	7	8	9
7. Auto Jump [mm] (No, 4.0 ~ 9.9,)	No	4	5	6
8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,)	3		_	
		1	2	3
		+/-	0	BS
P1 P2 P3				
P1 P2 P3				$\overline{2}$

9. -----

1. Auto Color Change (AC) (No, Yes,)	Yes	1		115
2. Auto Start (AS) (No, Yes,)	Yes			
3. A.S. in the Same Color (No, Yes,)	No			
4. A. S. after Auto Data Set (No, Yes,)	No		1	M
 Main Shaft Inching (0, 1, 2, 3, 4, 5, 6, 7, 8, 9,) 	0	5		
 M.Shaft Inching after ATH (2, 3, 4, 5, 6, 7, 8, 9,) 	4	7	8	9
7. Auto Jump [mm] (No, 4.0 ~ 9.9,)	No	4	5	6
8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,)	3		_	
		1	2	3
		+/-	0	BS
P1 P2 P3				

10. -----

		and the second		and a star
1. Auto Color Change (AC) (No, Yes,)	Yes			15
2. Auto Start (AS) (No, Yes,)	Yes		<u>). (7</u> .	
3. A.S. in the Same Color (No, Yes,)	No			
4. A. S. after Auto Data Set (No, Yes,)	No		1	7
5. Main Shaft Inching (0, 1, 2, 3, 4, 5, 6, 7, 8, 9,)	0	5		
6. M.Shaft Inching after ATH (2, 3, 4, 5, 6, 7, 8, 9,)	4	7	8	9
7. Auto Jump [mm] (No, 4.0 ~ 9.9,)	No	4	5	6
8. Jump Convert (No, 1, 2, 3, 4, 5, 6, 7, 8, 9,)	3		_	
		1	2	3
		+/-	0	BS
		1333		
P1 P2 P3				$\overline{}$



It makes the machine perform inching the number of set times at machine start after thread trimming.

When a stitch length is longer than the auto jump length being set, it will make the stitch perform auto jump.

"No" does not make auto jump.

When jump codes continue the number of set times and more consecutively, it converts the consecutive jump codes to frame stepping.

- Frame stepping moves the frame with the main shaft kept stopping.
- "No" does not make jump conversion.
- It is not possible to convert automatic jump.

It is not applied.

It is not applied.

11. -----It is not applied. No r 12 No 13. -----No No 14. ---- \bigtriangledown 15. Min. Revoluti (250 ~ 700,) 16. Upper T.Dete (0, 1, 2, 3, 4,) 17. Under T.Dete (0, 2, 4, 6, 8,) \triangle n [rpm] 600 7 8 9 2 ection (Unit) 4 4 5 6 (0, 2, 4, 6, 8,) 18. Under T.D. (Step Ratio) [%] (40, 50, 60, 70, 80,) 19. ATH (No, Yes,) 20. Picker Timing (Tail Length) (340 ~359, 0 ~ 60 deg,) 70 1 2 3 Yes +/- 0 BS 30 P1 P2 P3 12. -----It is not applied. 11. ----No 2 12 No 13. --No No 14. ----- \bigtriangledown 1... 15. Min. Revolution (pm) (250 ~ 700.) 16. Upper T. Detection (0, 1, 2, 3, 4) 17. Under T. Detection (Unit) (0, 2, 4, 6, 8) 18. Under T. D. (Slep Ratio) [%] (40, 50, 60, 70, 80.) 19. ATH (No, Yes.) 20. Picker Timing (Tail Length) (240 ~ 359, 0 ~ 60 deg.) \triangle 600 2 7 8 9 4 4 5 6 70 1 2 3 Yes +/- 0 BS 30 P1 P2 P3 13. -----It is not applied. 11. ----No U 12. ----No 13. ---No No 14 \triangle \bigtriangledown 15. Min. Revolution [rpm] (250 ~ 700,) 16. Upper T.Detection (0, 1, 2, 3, 4,) 17. Under T.Detection (Unit) (0, 2, 4, 6, 8,) 600 2 7 8 9 4 4 5 6 18. Under T.D. (Step Ratio) [%] (40, 50, 60, 70, 80,) 70 1 2 3 (40, 50, 60, 70, 80,) 19. ATH (No, Yes,) 20. Picker Timing (Tail Length) (340 ~359, 0 ~ 60 deg,) Yes 30 +/- 0 BS P1 P2 P3 14. -----It is not applied. 11. -----No 2 12. -----No 13. -----No 14. -----15, Min. Revolution (pm) 15, Min. Revolution (pm) 16, Upper T. Detection (0, 1, 2, 3, 4,) 17, Under T. Detection (Unit) (0, 2, 4, 6, 8,) 18, Under T. D. (Step Ratio) [%] (40, 59, 60, 70, 80,) 19, ATH (No, Yes,) 20. Picker Timing (Tail Length) (340 ~339, 0 ~ 60 deg.) \triangle \bigtriangledown 600 2 7 8 9 4 4 5 6 70 1 2 3 Yes +/- 0 BS 30 P1 P2 P3 15. Min. Revolution [rpm] Lower limit of running revolution 11. ---No 12. -----No Inching is not included. 13. -----600 No 14. ----- \triangle \bigtriangledown 15. Min. Revolution [rpm] (250 ~ 700,) 16. Upper T.Detection (0, 1, 2, 3, 4,) 17. Under T.Detection (Unit) (0, 2, 4, 6, 8,) 600 (250 ~ 700) 2 7 8 9 4 4 5 6 (0, 2, 4, 6, 8,) 18. Under T.D. (Step Ratio) [%] (40, 50, 60, 70, 80,) 19. ATH (No, Yes,) 20. Picker Timing (Tail Length) (340 ~3559, 0 ~ 60 deg,) 70 1 2 3 Yes

P1 P2 P3

30

+/- 0 BS

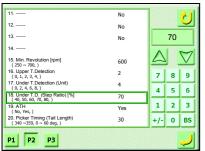
16. Upper T.Detection

12	No			0
13	No		2	
14			1	
15. Min. Revolution [rpm] (250 ~ 700,)	600	\square		\vee
16. Upper T.Detection (0, 1, 2, 3, 4,)	2	7	8	9
17. Under T.Detection (Unit) (0, 2, 4, 6, 8,)	4	4	5	6
 Under T.D. (Step Ratio) [%] (40, 50, 60, 70, 80,) 	70			بت
19. ATH (No, Yes,)	Yes	1	2	3
20. Picker Timing (Tail Length) (340 ~359, 0 ~ 60 deg,)	30	+/-	0	BS

17. Under T.Detection (Unit)

And the second		- Alexandre	Same	Sector Sector
11	No			115
12	No			
13	No		4	
14			1	\sim
15. Min. Revolution [rpm] (250 ~ 700,)	600			$\overline{\mathbf{\nabla}}$
16. Upper T.Detection (0, 1, 2, 3, 4,)	2	7	8	9
17. Under T.Detection (Unit) (0, 2, 4, 6, 8,)	4	4	5	6
18. Under T.D. (Step Ratio) [%] (40, 50, 60, 70, 80,)	70			
19. ATH (No, Yes,)	Yes	1	2	3
20. Picker Timing (Tail Length) (340 ~359, 0 ~ 60 deg,)	30	+/-	0	BS
P1 P2 P3				

18. Under T.D. (Step Ratio) [%]



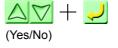
(40, 50, 60, 70, 80%)

(0, 1, 2, 3, 4)

(0, 2, 4, 6, 8)

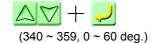
19. ATH

11	No			21
12	No	_		
13	No		Yes	
14			1	~
15. Min. Revolution [rpm] (250 ~ 700,)	600			\vee
16. Upper T.Detection (0, 1, 2, 3, 4,)	2	7	8	9
17. Under T.Detection (Unit) (0, 2, 4, 6, 8,)	4	4	5	6
18. Under T.D. (Step Ratio) [%] (40, 50, 60, 70, 80,)	70	<u> </u>	_	
19. ATH (No, Yes,)	Yes	1	2	3
20. Picker Timing (Tail Length) (340 ~359, 0 ~ 60 deg,)	30	+/-	0	BS
P1 P2 P3				



20. Picker Timing (Tail Length)

11	No			2
13	No		30	
14			1	2
15. Min. Revolution [rpm] (250 ~ 700,)	600	5	7	V
16. Upper T.Detection (0, 1, 2, 3, 4,)	2	7	8	9
17. Under T.Detection (Unit) (0, 2, 4, 6, 8,)	4	4	5	6
18. Under T.D. (Step Ratio) [%] (40, 50, 60, 70, 80,)	70			
19. ATH (No, Yes,)	Yes	1	2	3
20. Picker Timing (Tail Length) (340 ~359, 0 ~ 60 deq,)	30	+/-	0	BS
P1 P2 P3				1



When information of upper thread breakage is detected with the number of setting times and more consecutively, it will be regarded as a state of upper thread breakage.

- When the setting value becomes smaller, the sensitivity will become higher.
- \square "0" does not make detection.

When information of under thread breakage is detected the number of set times and more consecutively, it is regarded as a state of under thread breakage.

- When the setting value becomes smaller, the sensitivity will become higher.
- \square "0" does not make detection.

It adjusts sensitivity of thread breakage detection.

When the setting value becomes bigger, the sensitivity will become higher.

It makes the machine to perform automatic thread trimming at color change, end of embroidery, etc.

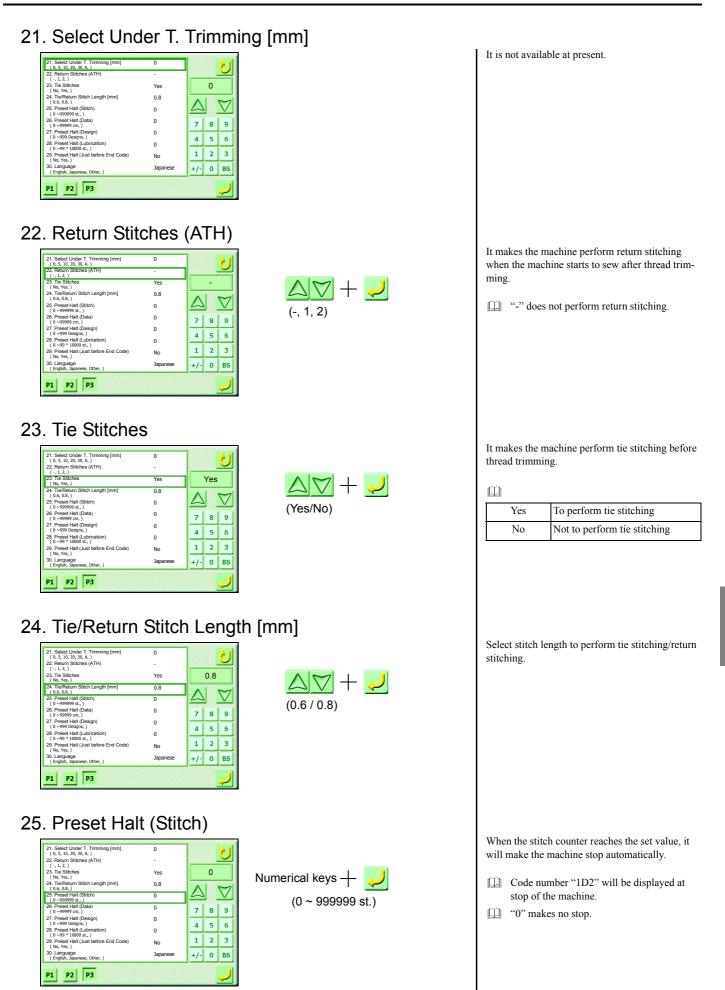
Ш

Yes	To perform thread trimming
No	Not to perform thread trimming

It adjusts the remaining thread length at thread trimming.

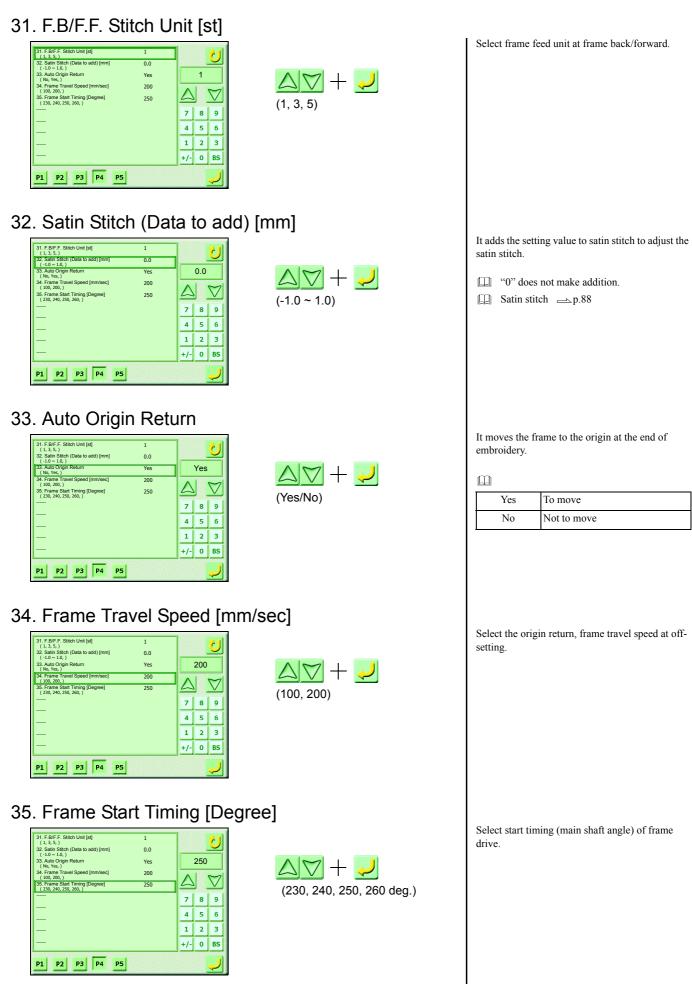
340 < 20 **二**> 60 Short Long

It is possible to make setting when "19. ATH" is set to "Yes"



P1 P2 P3

26. Preset Halt (Data) When frame moving amount reaches the set value, 1. Select Under T. Trimm (0, 5, 10, 20, 30, A,) 2. Return Stitches (ATH) U it will make the machine stop automatically. (0, 3, 40, ..., 22, Return Sitches (ATH) (-1, 2, 2) 23, Tic Sitches (No, Yes,) 44, Tie/Return Sitch Length [mm] (0.6, 0.8,) 25, Preset Halt (Sitch) (0 ~ 99999 st.,) 26, Preset Halt (Data) 7 ~ 99999 st.,) 0 Yes Numerical keys — Code number "1D2" will be displayed at 0.8 \triangle \bigtriangledown stop of the machine. 0 $(0 \sim 99999 \text{ cm})$ 7 8 9 "0" makes no stop. Preset Halt (Design) 0 ~999 Designs.) 0 4 5 6 Preset Halt (Lubrication) (0 ~99 * 10000 st.,) 0 123 29. Preset Halt (Just before End Code) (No, Yes,) No 30. Language (English, Japanese, Other,) lana +/- 0 BS P1 P2 P3 27. Preset Halt (Design) When embroidered designs reach the set value, it 21. Select Under T. Trimming [mm] (0, 5, 10, 20, 30, A,) 22. Return Stitches (ATH) (-, 1, 2,) 0 U makes the machine stop automatically. (-, 1, 2,) (bo, Yes,) 2.4. Tie (Fketurn Stich Length [mm] (0.6, 0.8.) (0.6, 0.8.) (2.6, 0.8.) (2.6, 0.8.) (2.6, 0.9.) (2.7. Preset Halt (Data) (0 ~ 9999 sr.,) (2.7. Preset Halt (Design) (1 ~ 999 Designs,) (2.9.) 0 Yes Numerical keys — Code number "1D2" will be displayed at 0.8 \triangle \bigtriangledown 0 stop of the machine. (0 ~ 999 Designs) 0 789 "0" makes no stop. 0 (0 -999 Designs,) (0 -999 Designs,) 28. Preset Halt (Lubrication) (0 -99 * 10000 st.,) 29. Preset Halt (Just before End Code) (No, Yes,) 4 5 6 1 2 3 No 30. Language (English, Japanese, Other, Japan +/- 0 BS P1 P2 P3 28. Preset Halt (Lubrication) When the stitch counter reaches the set value, it 21. Select Under T. Trimming [mm] (0, 5, 10, 20, 30, Α,) 22. Return Sitches (ATH) (-, 1, 2,) 23. Tie Sitches (No, Yes,) 24. Tie/Return Sitch Length [mm] (0, 6, 0, 8,) 25. Preset Halt (Sitch) (0 ~999999 σ.,) 26. Preset Halt (Data) U will make the machine stop automatically. 0 Yes Numerical keys Setting value multiplied by 10000 stitches 0.8 \triangle \bigtriangledown 0 Code number "OIL" will be displayed at (0 ~ 99 * 10000st.) (0 ~999999 st.,) 26. Preset Halt (Data) (0 ~99999 cm,) 27. Preset Halt (Design) (0 ~999 Designs,) 0 7 8 9 stop of the machine. 0 (U~999 Designs,) 28. Preset Halt (Lubrication) (U~99 * 10000 st.,) 29. Preset Halt (Just before End Coo (No, Yes,) 30. Lancuan 4 5 6 0 "0" makes no stop. 1 2 3 No It is effective when "36. Lubrication" is set 30. Language (English, Japanese, Other, +/- 0 BS Japa to "No". P1 P2 P3 29. Preset Halt (Just before End Code) It makes the machine stop automatically just 21. Select Under T. Trimming [mm] (0, 5, 10, 20, 30, A,) 22. Return Stitches (ATH) (-, 1, 2,) 0 21 before end of embroidery. (7, 1, 2,) 23. Tie Stitches (No, Yes,) 24. Tie/Return Stitch Length [mm] (0.6, 0.8,) 25. Preset Halt (Stitch) (0 ~999999 st.,) Yes No \bigtriangledown + \checkmark 0.8 Ш \triangle \bigtriangledown 0 (Yes/No) Yes To perform automatic stop (0~999999 st.,) 26. Preset Halt (Data) (0~9999 cm,) 27. Preset Halt (Design) (0~999 Designs,) 28. Preset Halt (Lubrication) (0~99 10000 st.,) 0 7 8 9 0 No Not to perform automatic stop 4 5 6 0 ~99 * 10000 st.,) reset Halt (Just before End 1 2 3 No It is possible to perform frame back after (No, Yes,) 30. Language (English, Japanese, Other,) +/- 0 BS Japanese stop of the machine. P1 P2 P3 30. Language Select display language of the screen. 21. Select Under T. Trimming [m (0, 5, 10, 20, 30, A,) 22. Return Stitches (ATH) (-, 1, 2) 0 0 (0, 3, 0) 20, 50, 70, 71 (1, 1, 2, 1) 23. Tie Stitches (MTH) (1, 1, 2, 2) 24. Tie/Return Stitch Length [mm] (0.6, 0.8, 1) 25. Preset Halt (Stitch) (0 - 939939 st.,) "Other" becomes different language depend-Japanese Yes \vee – ing on specification. 0.8 \triangle \bigtriangledown 0 (English, Japanese, Other) 26. Preset Halt (Data) (0 ~99999 cm,) 0 7 8 9 27. Preset Halt (Design) 0 4 5 6 28. Preset Halt (Lubrication) (0 ~99 * 10000 st.,) 29. Preset Halt (Just before End Code) 0 1 2 3 No Jap +/- 0 BS sh, Japanese, Othe



36	
31. F.B/F.F. Silder Unit [st] 1 (1, 3, 5, 5) 32. Sain Silder (Data to add) [mm] 0.0 (1, 2 - 1.0) 33. A (2 - 1.0) 200 (34. Frame Travel Speed [mm/sec] 200 (35. Frame Start Training [Degree] 250 (20, 20, 20, 20, 20, 0) 7 8 4 5 6 4 5 6 +/- 0 BS P1 P2 P3 P4 P5	It is not applied.
37	It is not applied.
31 F2B/F 5: Slich Unit [st] 1 (2, 35) Slich (Data to add) [mm] 0.0 (3) Auto Origin Return Yes (3) Auto Traval Speed [mm/sec] 200 (10) 200 Imministration (Degree) (10) 200 Imministration (Degree) (2) 7 8 (2) 7 8 (2) 7 8 (2) 7 8 (3) 200 Imministration (Degree) (20) Imministration (Degree) 250 (2) 7 8 (2) 7 8 (2) 200 1 (3) 200 1 (2) 200 1 (2) 200 1 (2) 200 1 (2) 7 8 (2) 1 2 (3) 1 2 (4) 5 6 (1) 2 3 (4) 5 6 (3)	
38	
31 F.B/F.F. Stitch Unit [st] 1 12 13.4.10.1 0.0 13.4.10.0 13.4.10.1 Ves (Mo, Yes.) 34.5.6 1 102.200, 200, 100 200 1 13.4.10.100 10.0 1 13.4.100.0100 Yes 1 (Mo, Yes.) 10.0 1 (102.200, 200, 200, 200, 200, 200, 200, 20	It is not applied.
39	
31 F.B/F.F. Silch Unit [st] 1 12 Sain Silch (Data to add) [rmi] 0.0 (1.0 - 1.0) 33 Auto Origin Return Yes (1.0 - 1.0) 35 Frame, 108 Speed [rmi/sec] 200 (5, Frame, 108 Seed [rmi/sec] 200 Image: 100 mi/sec] 200 (5, Frame, 108 Seed [rmi/sec] 200 Image: 100 mi/sec] 250 (7, 8, 9) 4 5 6 1 2 3 +/- 0 BS P1 P2 P3 P4 P5 Image: 100 mi/sec] Image: 100 mi/sec]	It is not applied.
40	
31. F.B/F.F. Stich Unit [st] 1 (1.3.5.) 32. Stain Stich (Data to add) [mm] 0.0 (1.0 ~ 1.0.) 33. Ato Origin Feturn Yes (Wo, Yes.) St. Frame Travel Speed [mm/sec] 200 (1.20, 20.) Timing [Degree] 250 25. (23.2, 36, 250., 260.) 7 8 9 1 2 3 +/- 0 BS P1 P2 P3 P4 P5	It is not applied.

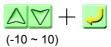
41. Boring		
41 Boring (B, V, G) (4) No 42 Boring Step (2) Step1 43 Coding (No, Yer.) No 44 Coding (No, Yer.) No 45 Network No 46. Serial Speed [poil (500, 12200, 3800, 12000, 3800, 12	(Yes/No)	Select whether boring device is equipped with the machine or not. Image: Select whether boring device is equipped Yes Equipped No Not equipped
42. Boring Step		
Intervention No [2] Boring Step Step1 [4] Boring Step Step1 [4] Conduct No [4] Kov Yes, No [4] Kov Yes, No [4] Kov Yes, No [4] Kov Yes, No [4] Serial Step1 Step1 [4] Kov Yes, No [4] Kov Yes, No [4] Backlash (X Avis) [rm1] 0.0 [-1] Costakish (V Avis) [rm1] 0.0 [-2] P3 P4	(Step1, Step3)	It processes stitch data when boring is performed. Image: Step1 Not to perform data processing Step3 To add mechanical offset amount 12 mm mm
43. Cording		
41. Boring (No. Yes.) No 42. Boring Step 1 Step 1 (42. Boring Step 2 Step 1 (45. Scriid Speed [poil (Soci, 1200, 38400,) No (46. Scriid Speed [poil (Soci, 1200, 38400,) No (47. ATH Start Timing [Degree] (-10 ~ 10.) 0 (47. Beckater (X Atte) [mm] (-0.5 ~ 0.5.) 0.0 (-10 ~ 10.) 1 2 (-0.5 ~ 0.5.) 50. Backater (Y Atte) [mm] (-0.5 ~ 0.5.) 0.0 (-10 ~ 10.) 1 2 (-10 ~ 10.) 0.0 +/- (-10 ~ 10.) 0.0 +/-	(Yes/No)	Select whether cording device is equipped with the machine or not.
44		
41 Berring (No. Yes.) No 42 Boring Step. Step.1 (45, Nethods) No Image: Step.1 43 Cording No (46, Yes.) No Image: Step.1 45 Nethods No (45, Nethods) No Image: Step.1 (45, Serial Speed [box] 38400 7 8 9 (47, ATH Start Trining[Degree] 0 Image: Step.1 4 5 6 10 4.5 6 1 2 3 4 5 6 11 2.3 4.5 6 1 2 3 4/- 0 BS P1 P2 P3 P4 P5 Image: Step.1 Image: St		It is not applied.
45. Network		
40. INCLIVIOIN 4. Bang Sapa (No. Yes,) 4. Coding (No. Yes,) 4. Coding	(Yes/No)	Select the state of network.

46. Serial Speed [bps]

41. Boring (No, Yes,) 42. Boring Step (Step1, Step3,)	No Step1			2
43. Cording (No, Yes,)	No	3	840	0
45. Network (No, Yes,)	No	\triangle		\bigtriangledown
46. Serial Speed [bps] (9600, 19200, 38400,)	38400	7	8	9
47. ATH Start Timing [Degree] (-10 ~ 10,)	0	4	5	6
49. Backlash (X Axis) [mm] (-0.5 ~ 0.5 ,)	0.0	1	2	3
50. Backlash (Y Axis) [mm] (-0.5 ~ 0.5 ,)	0.0	+/-	0	BS
	5			

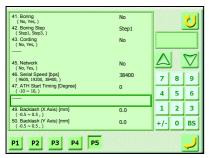
47. ATH Start Timing [Degree]

41. Boring (No, Yes,)	No	1		21
42. Boring Step (Step1, Step3,)	Step1			
43. Cording (No, Yes,)	No		0	
			1	M
45. Network (No, Yes,)	No	1		$\mathbf{\nabla}$
46. Serial Speed [bps] (9600, 19200, 38400,)	38400	7	8	9
47. ATH Start Timing [Degree] (-10 ~ 10,)	0	4	5	6
49. Backlash (X Axis) [mm] (-0.5 ~ 0.5,)	0.0	1	2	3
50. Backlash (Y Axis) [mm] (-0.5 ~ 0.5 ,)	0.0	+/-	0	BS
P1 P2 P3 P4 P5			1	
PI PZ P3 P4 P5				

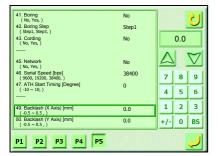


(9600, 19200, 38400)

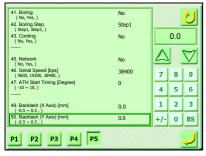
48. -----

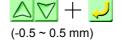


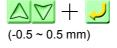
49. Backlash (X Axis) [mm]



50. Backlash (Y Axis) [mm]







Select transfer speed of serial connector.

It is possible to make setting when "Yes" is set to "45. Network".

Select drive start timing of the thread trimming motor.

When thread trimming is poor, make adjustment by changing setting value by ±1.

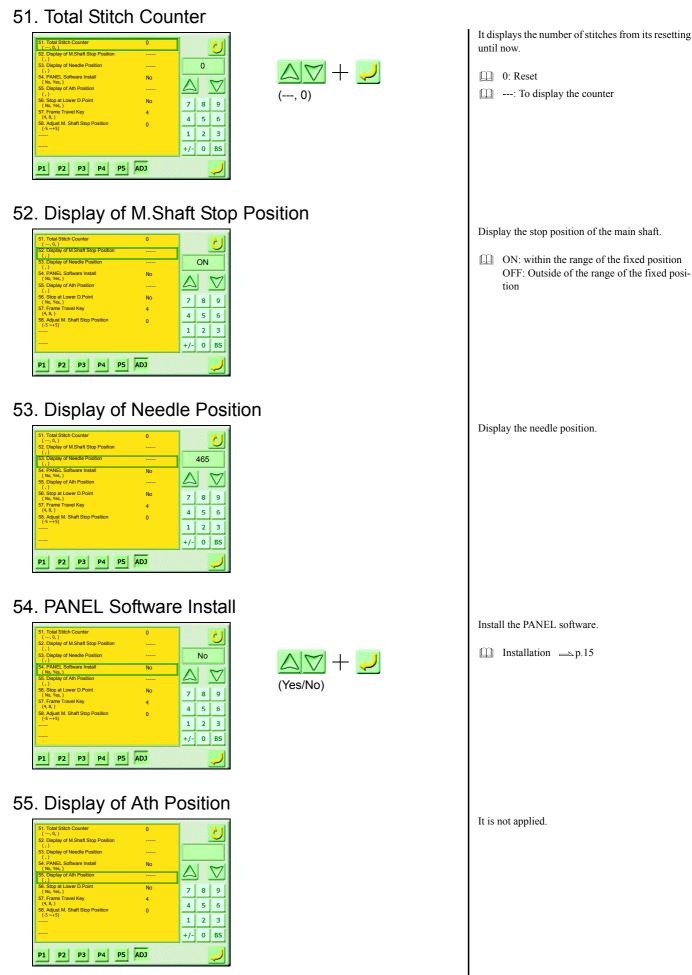
It is not applied.

It corrects mechanical error generated when movement of the X-axis drive system reverses.

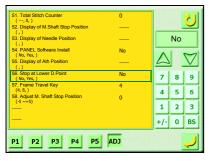
- \square "0" does not make correction.
- When correction is made, "32. Satin Stitch (Data to add)" will become invalid.
- □ Backlash → p.87

It corrects mechanical error generated when movement of the Y-axis drive system reverses.

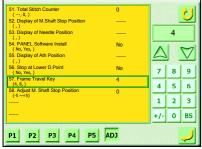
- "0" does not make correction.
- When correction is made, "32. Satin Stitch (Data to add)" will become invalid.
- □ Backlash → p.87



56. Stop at Lower D.Point



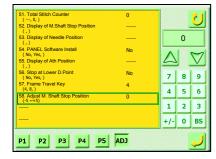
57. Frame Travel Key



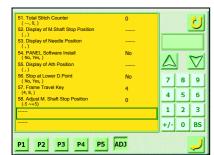
+

(Yes/No)

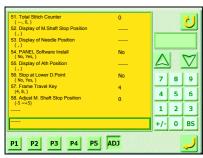
58. Adjust M. Shaft Stop Position

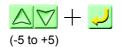


59. -----



60. -----



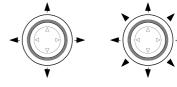


When stopping the machine with end code 2 (end of embroidery), it makes the machine stop at the lower dead point (pseudo-fixed position stop).

Ш		
	Yes	To perform stop at the lower dead point
		Not to perform stop at the lower dead point

When performing manual frame travel, frame origin memory, manual offset during stop of the machine, operate the machine after detaching border frame clips.

Effective directions of the frame travel key



4 directions

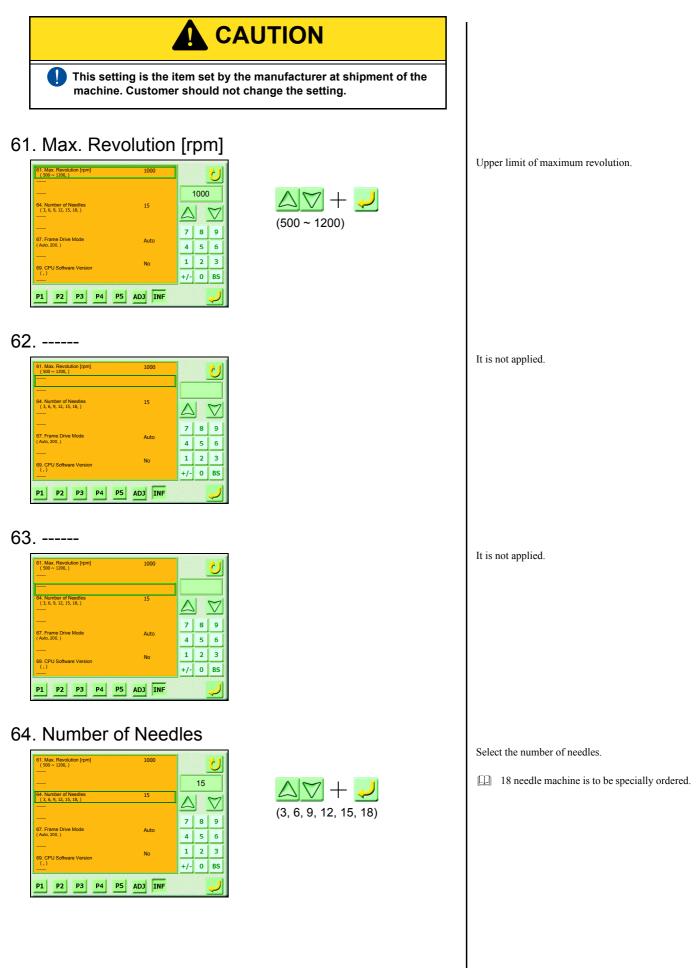
8 directions

Adjust stop position of the main shaft when it is misaligned.

It is not applied.

It is not applied.





82 CHAPTER 8 PARAMETER SETTING

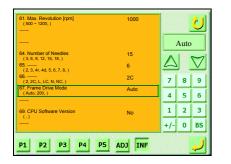
65. -----

61. Max. Revolution [rpm] (500 ~ 1200,)	1000			<u>U</u>
64. Number of Needles (3, 6, 9, 12, 15, 18,)	15			\bigtriangledown
67. Frame Drive Mode	Auto	7	8	9
(Auto, 200,)	Auto	4	5	6
69. CPU Software Version	No	1	2	3
(,) 		+/-	0	BS
P1 P2 P3 P4 F	5 ADJ INF			

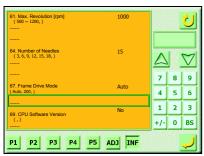
66. -----

61. Max. Revolution [rpm] (500 ~ 1200,)	1000			U
64. Number of Needles (3, 6, 9, 12, 15, 18,)	15			\bigtriangledown
		7	8	9
67. Frame Drive Mode (Auto, 200,)	Auto	4	5	6
 69. CPU Software Version	No	1	2	3
(,)		+/-	0	BS
P1 P2 P3 P4 P	5 ADJ INF			

67. Frame Drive Mode

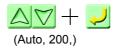


68. -----



69. CPU Software Version

61. Max. Revolution [rpm] (500 ~ 1200,)	1000			2
		0.	.53F	L
64. Number of Needles (3, 6, 9, 12, 15, 18,) 	15	\triangle		\bigtriangledown
 67. Erame Drive Mode		7	8	9
(Auto, 200,)	Auto	4	5	6
69. CPU Software Version		1	2	3
- (,) 		+/-	0	BS
P1 P2 P3 P4 P5	ADJ INF			J



It is not applied.

It is not applied.

This is a selection of usual frame drive mode or the mode to reduce looping.

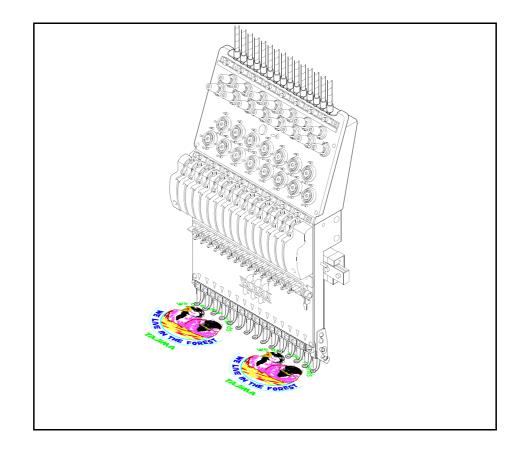
 \square It is not possible to perform setting in .

A	uto	Usual frame drive mode			
200		Frame drive mode to reduce loop- ing			
200 Max 850rpm		50rpm	Upper limit to low speed rpm550rpm		

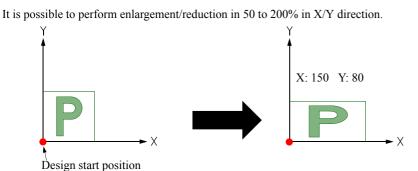
It is not applied.

Display the version of CPU software.

CHAPTER 9 OUTLINE OF FUNCTIONS

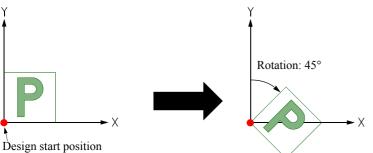


1. DESIGN SCALE UP/DOWN



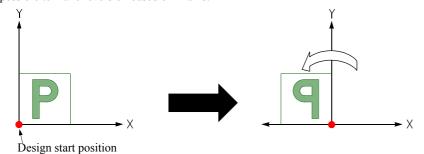
2. ROTATION

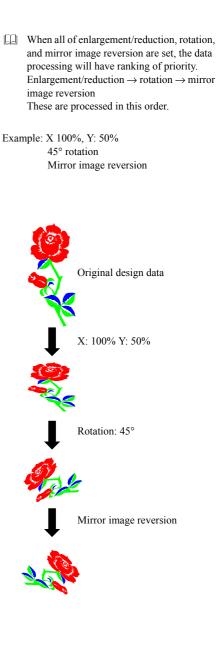
It is possible to rotate a design up to 359° in 1° unit.



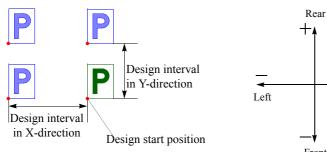
3. MIRROR IMAGE REVERSION

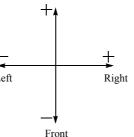
It is possible to make reversion based on Y-axis.

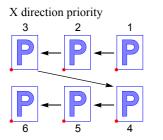


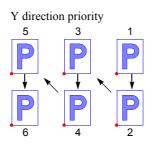


4. REPEAT

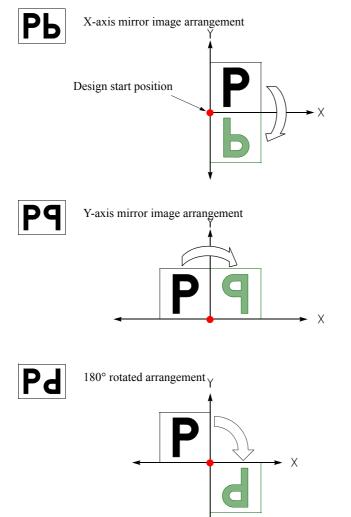








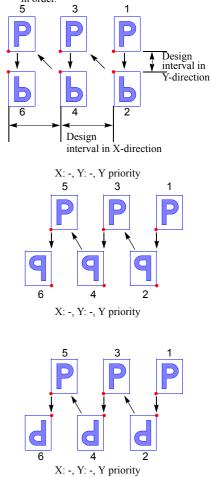
5. CONVERTED ARRANGEMENT



The repeat direction will be decided by +/of amount of design interval.

- Embroidering order differs depending on priority direction.
- The XY design interval in the left illustration is minus direction.

 Converted arrangement arranges and repeats the design as it is set as the initial setting in odd-numbered times, and design arranged by mirror/rotation in even-numbered times in order.
 3 1



6. MANUAL OFFSET

This function returns the embroidery frame to the original position after stopping the machine at a free setting point and moving the embroidery frame forward from the free setting point by manual frame travel.

1. It performs manual thread trimming after it makes the machine stop at the free setting point (A).

2. Move the embroidery frame forward (B) by manual frame travel for confirming the embroidery design, etc.

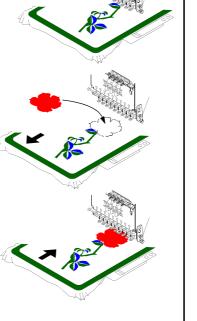
- 3. When starting the machine, it will move to the free setting point (A), and the embroidery will be continued.
- 7. AUTOMATIC OFFSET

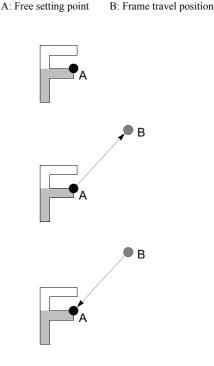
This function moves the embroidery frame forward automatically at the end position of design.

1. The machine stops at the end position of the frame (B) to perform thread trimming, and the embroidery frame moves to the offset start position (D) through the middle position (C).

2. Exchange the cloth or frame.

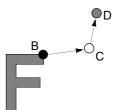
3. When starting the machine, the embroidery frame will move to the design start position (A) through the middle position (C), and the embroidery will be continued.



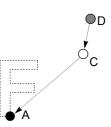


A: Design start position

- B: End position of design
- C: Middle position
- D: Offset start position



When there is no middle position (C), the frame will move directly to the offset start position (D).



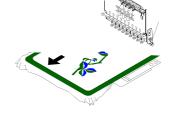
When there is no middle position (C), the frame will move to the design start position (A).

8. OFFSETTING AT AUTOMATIC COLOR CHANGE

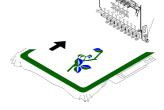
This function makes the embroidery frame move forward automatically at color change.

Condition: Offsetting at automatic color change is set, automatic offset is set, "Yes" is set to "Automatic color change (AC), automatic start (AS), and ATH" of parameter.

 The machine stops at the color change point (B) to perform thread trimming, and the embroidery frame moves to the offset start position (C) through the middle position (A).

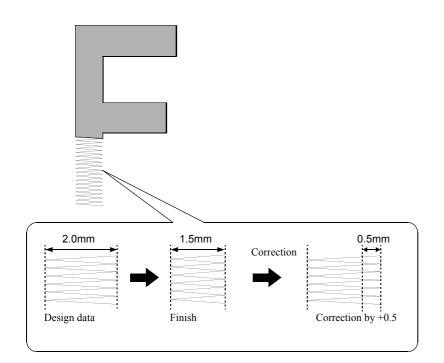


2. When starting the machine, the embroidery frame will move to the color change point (B) through the middle position (A), and the embroidery will be continued.

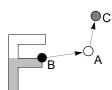


9. BACKLASH

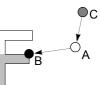
This function corrects drive error generated when direction of stitch data reverses (reversion of polarity).



- A: Middle position
- B: Color change point
- C: Offset start position



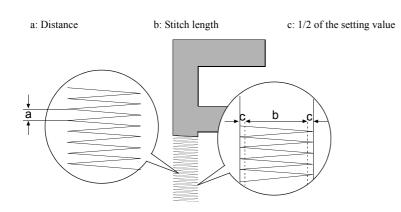
When there is no middle position (A), the frame will move directly to the offset start position (C).



- When there is no middle position (A), the frame will move directly to the free setting point (B).
- It is possible to correct stitch of each X direction and Y direction by -0.5 to +0.5 mm.

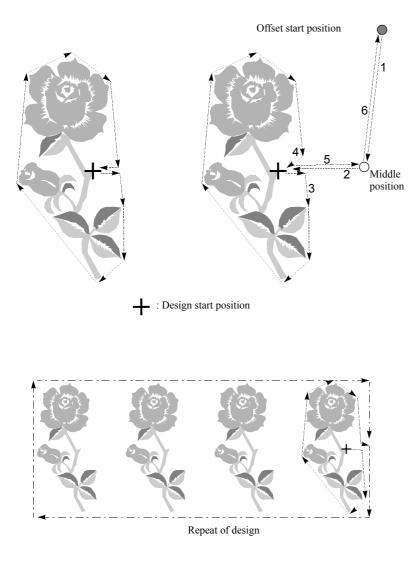
10. SATIN STITCH

This function expands satin stitch length.



11. TRACE

This function makes the frame move along the outer circumference of the design that has been set.

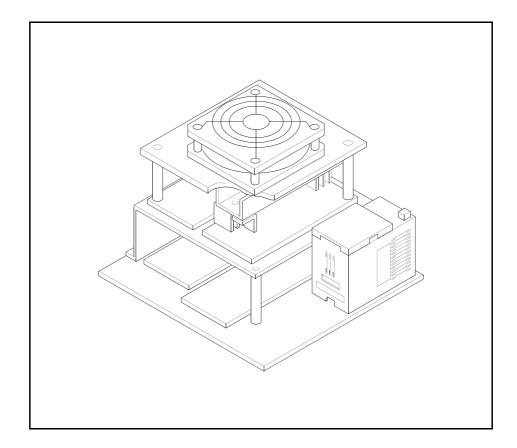


- Density for distinction When a distance (a) is 1 mm or less, the machine recognizes it as a satin stitch.
- Data to be added
 A half (c) of the set value in parameter "32.
 Satin Stitch (Data to add) [mm]" is added
 both sides of stitch (b).

- Trace makes the frame move to each apex of the outer circumference of the design as if a rubber ring was hanged at each apex.
- When there is an offset position, the frame will move to offset start position → middle position → design start position → outer circumference → design start position → middle position → offset start position.

When repeat setting is made, whole designs will be traced after tracing the first design only.

CHAPTER 10 ELECTRO-COMPONENT PARTS



1. POWER SUPPLY/DRIVER UNIT

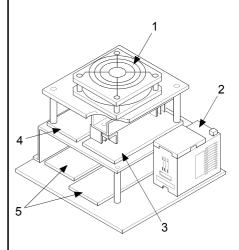
O not put an object that blocks wind flow of the cooling fan. Inside of the box will overheat to cause the machine to malfunction, which will become a cause of trouble.

1	Cooling fan
2	Inverter
3	X/Y-axis driver
4	Head card
5	DC power supply

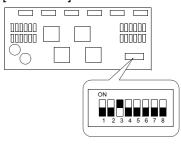
2. DIP SWITCH

O Do not change switch setting of the DIP switch. The machine will malfunction, which will become a cause of trouble.

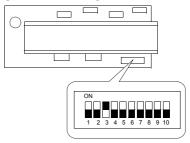
CAUTION



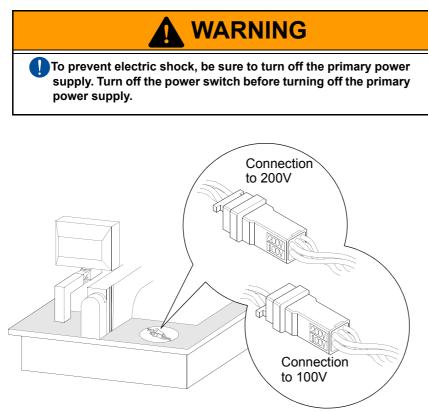
[Head card]



[X/Y-axis driver]

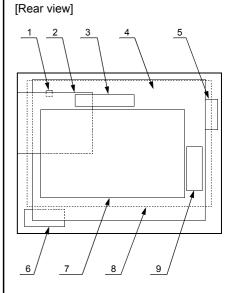


3. SWITCHING OF POWER SUPPLY SPECIFICATION



4. OPERATION PANEL BOX

1	DIP switch (SW1)
2	FDD
3	Backlight inverter
4	CPU-E card
5	Touch panel cable extension card
6	Frame travel switch card
7	RISC card
8	Touch panel
9	Regulator card





 \square Do not change setting of the DIP switch.

CHAPTER 11 TROUBLESHOOTING



1. IF MACHINE OPERATION IS INTERRUPTED



There are two main machine stop factors: one is stop by occurrence of error and another is stop by normal stop factor. When the machine operation is interrupted with code number displayed on the screen, carry out the troubleshooting referring to the code chart below.

Stop by occurrence of error

 \square If a code number of 300 series is displayed, contact your local distributor.

Code No.	Stop Factor	Corrective Action	
211	The fixed position signal (main shaft Z signal) is not detected.	Return the main shaft to the fixed position. Check the encoder signal.	
221	The frame has traveled exceeding the travel limit posi- tion. (Left direction)		
222	The frame has traveled exceeding the travel limit posi- tion. (Right direction)	Move the frame manually so that the design fits in the embroi- dery area.	
223	The frame has traveled exceeding the travel limit posi- tion. (Front direction)		
224	The frame has traveled exceeding the travel limit posi- tion. (Rear direction)		
225	Stitching has exceeded the embroidery space. (In case of cap frame spec.)		
228	Table up/down operation was performed when the frame was positioned forward.	Move the frame to the rearmost.	
281	The target needle position is not detected even after 15 seconds after start of color change.	Return the needle position to make the correct display. Check or replace the potentiometer (needle position sensor).	
201	The machine has detected thread breakage.	Check upper and under threads.	
291	Tension base card is bad	Replacement of tension base card	
293	Under thread breakage has been detected.	Check the under thread.	
2B1	No response is received for 5 seconds since the opera- tion was started using a serial interface. (A device is not connected to the serial interface.)	Check connection of the device. Correct the design data.	
2B2	Tajima code complement data error (The same + and - numbers exist in one stitch data).		
2B3	Data exists in an end code.	Correct the design data.	
2B4	Function code error		
2B7	Data is not set.	Perform data setting.	
2B8	The pre-reading buffer has become empty and no data is output.	During operation: Lower the r.p.m. During frame forward operation: Wait until the design data is all read.	
2B9	Memory write error	Check CPU card or Panel card. Replace it if necessary.	
2BA	Memory capacity over	Delete unnecessary designs registered in memory.	
2BB	Frame back movement exceeded the allowable range.	Do not perform further frame back.	
2BC	No design is registered in the memory.	Register designs in the memory.	

Code No.	Stop Factor	Corrective Action
2CB	The design data is too big to be put in the set embroidery space.	Change to smaller design data.
2CC	A floppy disk was inserted during operation.	Take out the floppy disk.
2CE	Stop by safety device	Check safety, and remove the obstacle.
2E3	The power supply was shut off during operation (including power shut off by the emergency switch).	Execute power resume operation.
311	Encoder A signal does not change for 5 seconds. Abnormality of motor, motor belt	Check encoder or encoder signal lines. Check the motor or motor belt. Check the main shaft driver for excitation.
312	Encoder Z signal status does not change.	Check the encoder or encoder signal lines.
316	A main shaft driver error signal is detected.	Replace the main shaft driver unit or main shaft motor.
322	An X-axis motor driver error signal is detected.	Replace the X-axis driver.
323	An Y-axis motor driver error signal is detected.	Replace the Y-axis driver.
382	The needle position signal status during color change does not change for 1 second or more.	Check the color change motor and power supply circuit. Check the potentiometer (needle position sensor).
383	No needle position signal is detected during rotation of the main shaft.	Check the potentiometer (needle position sensor).
3A6	ATH knife retractable position has become nonuni- form.	Check the position of ATH movable knife.
3A8	Thread holding driver error signal is detected.	Replace the head card.
3B1	No input signal is given when performing serial input	Check the output of the external device. Check the cable connection.
3C1	Contact error of the bar switch or start/stop switch, breakage of the switch harness, or bad connection of the connector	Check the connector and the connecting terminal. Replace the limit switch or switch assembly.
3D1	Backup battery voltage has decreased.	Turn on the power supply of the machine and charge the bat- tery. Set parameters and input designs again.
3D3	There is abnormality in power supply.	Check the wiring. If there is no abnormality, replace the trans- former.
B01	Floppy disk format has an error.	Format the floppy disk. Use a new formatted floppy disk.
DUI	Read/write error occurred.	Copy other designs to a new floppy disk and dispose of the old floppy disk.
B02	Floppy disk management information has an error.	Copy the floppy disk, and do not use the floppy disk in which error occurs.
B03	The write protect window of the floppy disk is open.	Close the write protect window.
B04	No floppy disk has been inserted.	Insert a floppy disk.
BC1	Selected design is not found on the floppy disk. No design is registered on the floppy disk.	Select other design.
BC2	The set file name has already been used for the design registered in the floppy disk.	Change the file name.
BC4	Design data was not correctly written from the memory to the floppy disk.	Retry writing.

Stop due to Normal Stop Factors

 \square Stop by the code numbers (100-series) described below is not caused by occurrence of error.

Code No.	Stop Factor	Corrective Action	
1B1	Stop due to a frame stepping code.		
1B2	Stop due to a stop code.	These stops are not caused by abnormality or failure.	
1B3	Stop due to stop code 1.	Perform "start operation" or "frame back/forward opera- tion". Alternatively, press any operation key (excluding	
1B4	Stop due to thread trimming code.	manual frame travel key) to continue the machine opera- tion.	
1B6	Stop due to an automatic free setting offset code.		
1C1	Stop due to the bar switch/stop switch.	Perform "start operation" or "frame back/forward opera-	
1C2	Stop due to the manual ATH or needle bar operation.	tion".	
1D2	Stop by preset halt (except lubrication)	Reset. Total counterp.73, p.74	
OIL	Preset halt (lubrication)	Perform lubrication to the corresponding spots, and reset the machine. Total counter $rac{-}{=}p.74$	

2. IF TROUBLE OCCURS

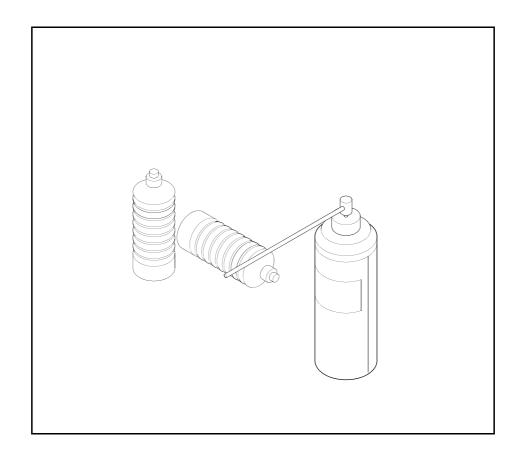


Adjustment includes some complicated works. Consult your local distributor before working.

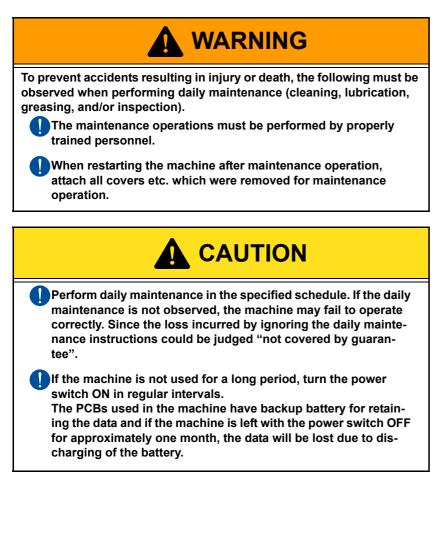
Cause of troubles and adjustments

	Cause	Adjust	
	Loose or broken belts	Adjust the belt tension or replace the belt.	
Machine cannot start	Needle position signal, NOT detected.	Adjust the needle position so that needle position is properly indicated in the manual color change section on the operation panel.	
	Alarm lamp on the driver box (unit) is ON.	Switch the power from OFF to ON.	
	Poor connection of power supply box connectors.	Securely connect the connectors.	
St	Loose or soiled belt	Adjust the belt tension or clean the belt.	
Stop position error	Galling of driving parts	Replace the driving parts for needle bar/rotary hook. or make adjustment.	
	Stop position is incorrect.	Adjust the position.	
Incorrect color changing	Position of take-up lever is wrong.	Adjust the position of the take-up lever at the stop position so that its position is the same as others.	
enanging	Needle position NOT detected.	Adjust the needle position so that needle position is properly indicated in the manual color change section on the operation panel.	
Jump error	Incorrect positioning of parts related to needle bar drive system	Adjust the attaching position of the needle bar reciprocator set with the upper dead point stopper.	
	Incorrect positioning of frame drive belt	Adjust the belt tension.	
	Malfunctioning of frame drive system	Replace/adjust the parts.	
Design displaced	Overall frame weight is excessive.	Lower the r.p.m.	
		Replace the drive unit.	
	Drive unit (X, Y-axes) defective	Replace the X-axis/Y-axis drivers.	
	Wrong needle-rotary hook timing or improper gap	Adjust the timing or gap.	
	Wrong needle bar lower dead point	Adjust the lower dead point.	
Thread breaks	Scratches on rotary hooks, presser feet, or on thread passage areas	Remove the scratches.	
	Incorrect upper/lower thread tension	Adjust the tension.	
	Repeated stitching at the same point	Correct the data.	
	Incorrect take-up lever timing	Readjust the take-up lever driving cam timing.	
	Thread is not trimmed.	Adjust the ATH knife position.	
ATH	Thread frayed at the beginning of embroidery	Picker timing(p.72)Adjust the thread trimming length by set- ting.	
	Poor tensioning of upper thread	Adjust the tension.	
Needle bar acti- vates even if the	Tension base card is faulty.	Replace the tension base card.	
tension base switch is set to the "bottom" posi- tion.	Poor adjustment for jumping		

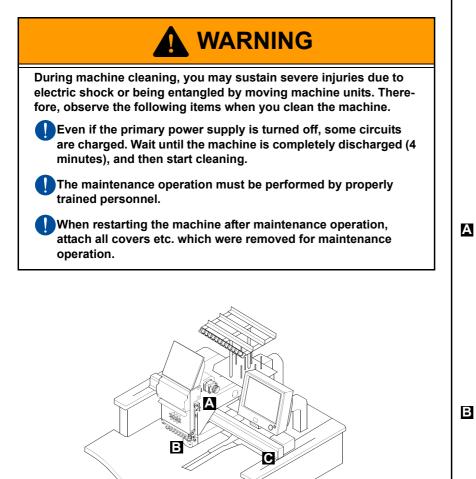
CHAPTER 12 MAINTENANCE

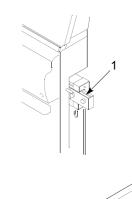


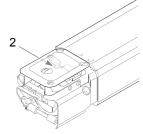
1. WARNINGS AND PRECAUTIONS



2. CLEANING

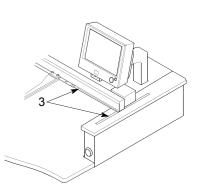






Cleaning area	Cleaning cycle
(1) Case linear section	Once/week
(2) ATH section	Everyday
(3) X-axis drive system, Y-axis drive system	Once/2 weeks

С



3. LUBRICATION



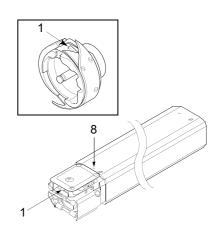
During machine lubricant, turn off the power switch. You may sustain severe injuries due to being entangled by moving machine units.

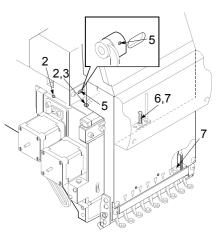


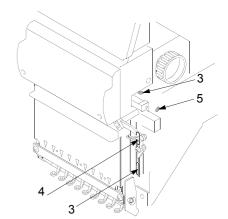
Keep the lubrication cycles as shown below. Deviated lubrication cycles may cause thread breakage.

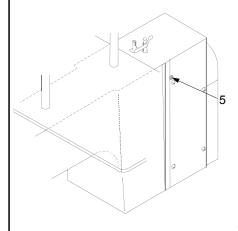
When supplying lubricating oil, use only Tajima's genuine SF oil or equivalent (#150 spindle oil: ISO viscosity grade= VG 18).

Lubrication points	Lubrication cycle	
(1) Rail on rotary hook	Every 3 to 4 hours of operation	
(2) Presser foot reciprocator(3) Needle bar drive shaft	Once/day	
(4) Presser foot drive shaft(5) Inside of the arm(6) Needle bar (lubricate from the slit of the upper cover)(7) Felt packing	Once/week	
(8) Inside of the cylinder bed	Once/3 months	









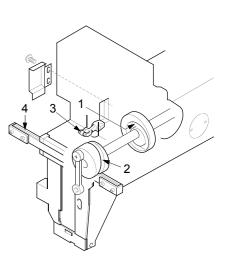
4. GREASING

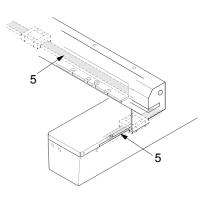
WARNING

During machine greasing, turn off the power switch. You may sustain severe injuries due to being entangled by moving machine units.



Greasing points	Greasing cycle
(1) Presser foot cam(2) Take-up lever drive cam(3) Roller of take-up lever	Once/3 months
(4) Case linear section(5) X/Y-axis drive system	Once/6 months





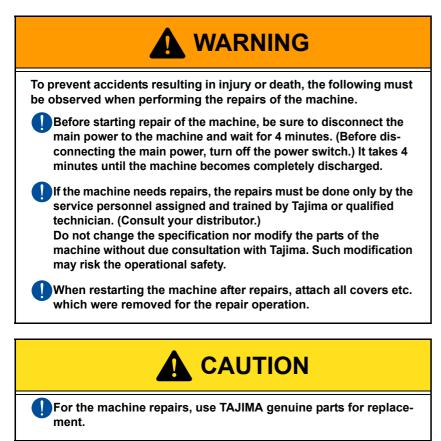
5. INSPECTIONS

WARNING

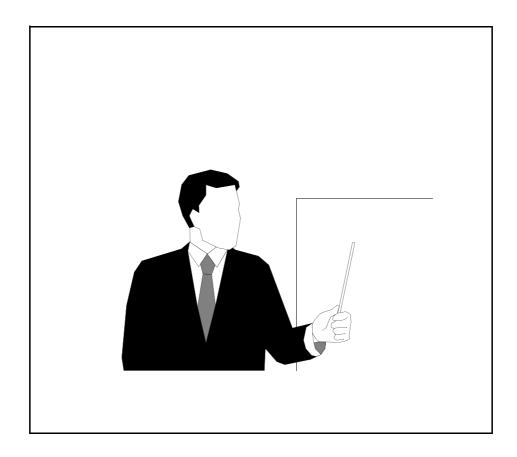
During machine inspection, turn off the primary power supply. (Before disconnecting the primary power supply, turn off the power switch.) You may sustain severe injuries due to being entangles by moving machine units.

Inspection point	Contents	Cycle
(1) Each belt of main shaft drive system	Tension and wear of belt, existence of crack	
(2) Each belt of X/Y-axis drive system	Tension and wear of belt, existence of crack	Once/3 months
(3) Rotating and sliding sections	Degree of wear	

6. REPAIR



TERMINOLOGY



Α

ABSOLUTE ORIGIN

A mechanical origin to detect the absolute origin of embroidery frame

AFC

Abbreviation of Automatic Frame Changer. Device for performing automatic embroidery continuously against piece goods fabric to be embroidered

AFC VALVE

Air valve that activates AFC.

APPLIQUE

The method to sew colored clothes, etc. that are cut to various shapes on the material.

ATH

Abbreviation of Automatic Thread Trimming and Holding Device

AUTOMATIC FRAME TRAVEL

Automatic frame travel by inner processing in such an occasion as at the end of embroidery or during set of offset.

AUTOMATIC JUMP

To make jump automatically when a stitch length exceeds the setting value.

AUTOMATIC LUBRICATION SYSTEM

Device to lubricate to each section of machine head automatically (option).

В

BOBBIN CHANGER

A device attached to under face of table to change bobbins automatically (option)

BORDER FRAME

A kind of embroidery frames It holds cut cloth (material) of some extent of size to be stretched.

BORING DEVICE

A device that makes hole(s) on the cloth (material) by knife attached to the needle bar to add values to embroidery

BUFFER (BUFFER MEMORY)

Buffer memory media to smooth input/output of data

С

CAP FRAME

A kind of embroidery frame for embroidery on cap (option). There are two types: one is wide cap frame and another is semiwide cap frame. Wide cap frame enables embroidery on wider range in circumference direction compared with semi-wide cap frame

CHECK SUM

A kind of measures to detect error of data transfer or saved (memory) contents.

CLEANUP

To make preceding and seceding stitches absorb to remove fine stitch of design data.

CODE FORMAT

Data type (tape code) for data input

COILING

To coil cord-shaped material around core thread to be sewn on the material to be embroidered.

CORDING DEVICE

Device to sew corded material to material to be embroidered (option).

CURSOR

A mark that indicates the position where character or value is to be input/displayed on the screen. Some of marks blink ore reverse character

D

DATA CONVERSION

To reduce/enlarge, rotate, or reverse the original design data.

DATA INPUT

To set design data that corresponds to design to sew

DATA SET

Operation to decide a series of setting contents in data input

D-AXIS

Driving shaft to rotate sewing needle or nipple (TMCE series)

DESIGN DATA

Data to embroider design It consists of design and data such as embroidery mode.

DESIGN INTERVAL

Amount of movement (mm) when one design moves to the next design in repeat embroidery of the same design

DESIGN INTERVAL FUNCTION

Moving method when moving one design to the next design in embroidering the same design repeatedly. Moving method includes by stitch and by frame stepping (frame stepping only for TMLH series)

DIP SWITCH

A small slide switch to change conditions of machine movements

DSW

Abbreviation of Dual in Package Switch. Refer to DIP switch.

Ε

EMBROIDERY FRAME

A general term of frames that hold material to be embroidered such as cloth, leather, etc. 3

END CODE

There are the code that indicates the end point of embroidery (end code 2) and the code that indicates the pause in designs to be repeated (end code 1).

EXCITATION

To generate magnetic power by sending electric current into coil such as electric magnet, etc.

F

FDD

Abbreviation of Floppy Disk Drive Refer to Floppy Disk Drive

FIXED PITCH MOVEMENT

To move the frame to right or left direction (X-axis direction) by preset head pitch (head interval)

FIXED POSITION

It is the regular stop position, and is indicated by angle of the main shaft of the machine

FLOPPY DISK

An external memory device of which round shaped polyester surface is pasted with magnetic powder It is used for storing design data, etc.

FLOPPY DISK DRIVE

A device to write or read data or program of floppy disk

FRAME BACK

To move the embroidery frame only to the returning direction of stitches with the needle bar(s) stopped

FRAME FORWARD

To move the embroidery frame only to the advancing direction of stitches with the needle bar(s) stopped

FRAME LIMIT SWITCH

Switch to limit the embroidery range

FRAME LIMIT

The embroidery space limited by the frame limit switches

FRAME

Refer to embroidery frame

FRAME STEPPING

To move the embroidery frame only with the main shaft of the machine kept stopped during embroidery

FUNCTION CODE

A control code to specify function or action of the machine

Η

HALF CUT

To cut only the upper material of piled materials (usually two pieces) by laser irradiation

INCHING

Very slow rotation of the main shaft when the machine starts or before it stops.

J

JUMP

Not to activate needle bar by cutting off the driving force from needle bar driving mechanism. It is possible to generate a longer stitch than the maximum length of one stitch by jumping during operation. When the machine stops, it is always in a state of jumping.

L

Abbreviation of Liquid Crystal Display

LED

Abbreviation of Light Emitting Diode

LOOPING

In a state of remaining upper thread on fabric with incomplete tightening due to poor pulling of upper thread by take-up lever.

Μ

MANUAL FRAME TRAVEL

To move the embroidery frame to a free setting position by key switch operation.

MANUAL THREAD TRIMMING

To activate the ATH by key switch operation to trim thread(s).

MARKING

To draw illustrations or letters by scorching the surface of the material by laser irradiation (only when laser processing). To make the basting data (marking design) for positioning the material to be embroidered in applique embroidery or placing

M-AXIS

Drive shaft to rotate nipple or bobbin (TMLH series)

MEMORY DESIGN

Design data written in the memory

MEMORY

Internal memory device

MEMORY REGISTRATION

To write to the memory (memory writing)

MEMORY WRITING

To write to the memory (memory registration)

MODE

Contents of setting, operation

Ν

NEEDLE BAR SELECTION

To set orders of needle bars to be used

NIPPLE

Part to press material to be embroidered in LH head. Attachment suitable for material to be sewn such as cord, tape. etc. is attached

NIPPLE STROKE

Stroke of nipple in up and down directions

NMI

Abbreviation of Non-Maskable Interrupt. The interrupt factor that cannot be inhibited and is used when computer signal is input.

NUMERICAL KEYS

Numerical key switches of 0 to 9

0

OFFSET START POSITION

A free setting position that makes the embroidery frame wait temporarily in offset setting.

ORIGIN

The position where trace or start/frame forward was made at the beginning after data set (start position of design).

* When automatic free setting offset is set, the offset start position will become the start position.

Ρ

POLARITY

Posture of a design when embroidering.

R

RAM

Abbreviation of Random Access memory

RESET

To return the control system of the machine that stopped movement by stop factor to the previous condition to its stop.

RETURN STITCHING

It prevents misstitching or fraying, and is executed when the machine starts to sew.

ROM

Abbreviation of Read Only Memory

RS232C CONNECTOR

Connector for data communication

S

SEQUIN

A kind of decorative materials to be sewn on clothes, etc. Thin round plate(s) that have hole at the center to be sewn. **SOLENOID**

A kind of drive devices when the power is turned on, and it is a kind of products for which electric magnet is applied **SPEED CODE**

Design data code to switch embroider speed (high speed/low speed)

STEP

Sequence of color changes for one design

STEP

To advance value one by one

STITCH DATA

Data set for each one stitch, which consists of X•Y data, function code, and speed code (D series, TLFDII). **STOP AT LOWER D. POINT (PSEUDO-FIXED POSITION)**

To stop the machine with needle stuck in cloth at end of embroidery (end code 2) (Stop at the lower dead point).

Т

TAJIMA COMPLEMENT ERROR

Error related to composition of X and Y data (It is composed of 10 values of +/-1, +/-3, +/-9, +/27, +/-81). It means two values that are complemental each other (for example +27 and -27) exist on X or Y data at the same time

TAJIMA TWO-WAY NETWORK SYSTEM (OPTION)

System that performs centralized control of plural machines using a personal computer. It can transmit design data or receive running condition of each machine.

TAPE CODE

Data type (code format) for data input

THE NUMBER OF STITCHES

The number of needle sticks when embroidering

TUBULAR GOODS FRAME

A kind of embroidery frames. It mainly holds trainer, T-shirt, etc. to be stretched

U

UBC

Abbreviation of Under thread bobbin changer. Refer to bobbin changer.

UNDER THREAD RELEASE

Action that makes the frame perform slight reciprocating movement to pull out under thread for loosening its tension before thread trimming not to trim under thread by other sections than the thread trimming section.

V

VERSION NUMBER

The number that shows developing order of software or hardware of the machine

W

WRITE DESIGN NUMBER

Memory registration number to set for data management when design data is written (memorized).

Х

X DATA

The data that makes the embroidery frame move right/left direction (X direction) by the X-axis drive system. The value displayed as X data indicates movement amount (mm), and the symbol indicates movement direction (+left, -right).

X-AXIS DRIVE SYSTEM

The drive system that makes the embroidery frame move to right and left directions against the front of the embroidery machine. 2

Υ

Y DATA

The data that makes the embroidery frame move front/rear direction (Y direction) by the Y-axis drive system. The value displayed as Y data indicates movement amount (mm), and the symbol indicates movement direction (+front, -rear).

Y-AXIS DRIVE SYSTEM

The drive system that makes the embroidery frame move to front and rear directions against the front of the embroidery machine.

Ζ

Z-AXIS

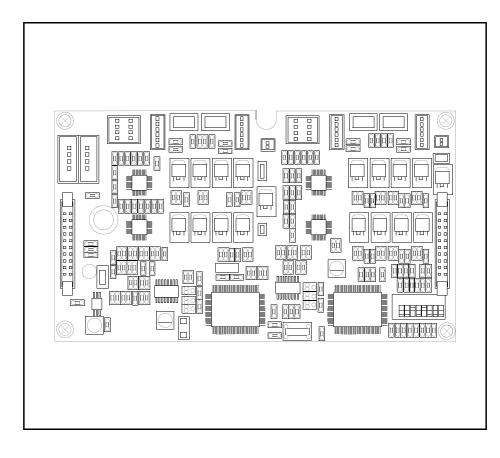
Drive shaft to change needle height (TMCE series)

ZIGZAG SWING EMBROIDERY

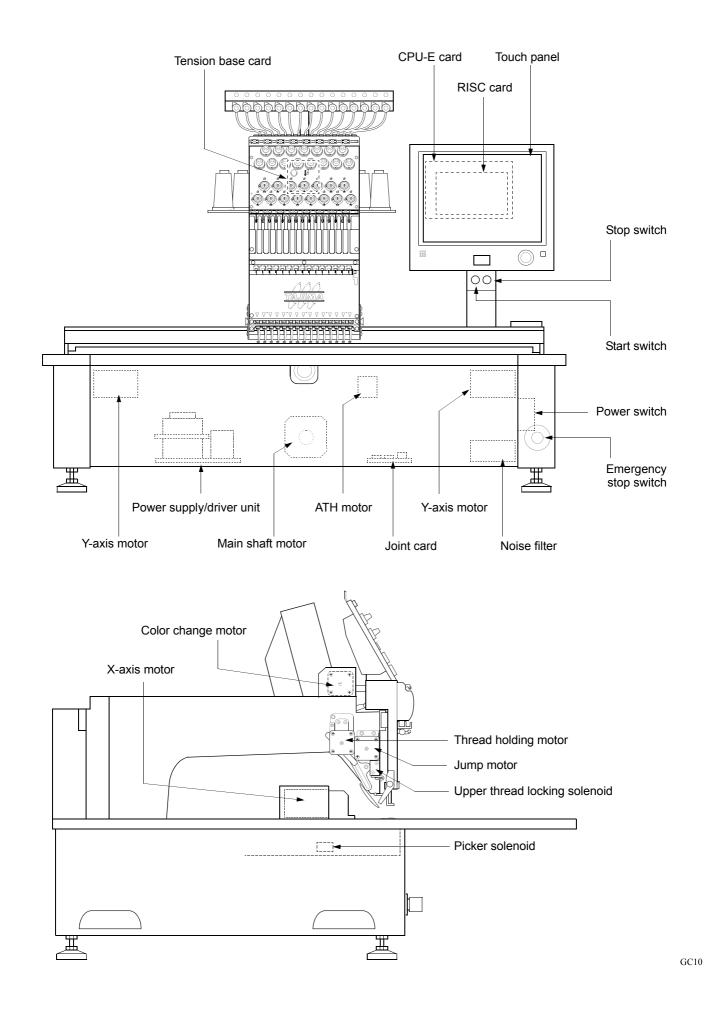
To sew cord-shaped material by zigzag swing. * Needle are not located to cord-shaped material generally.

TERMINOLOGY

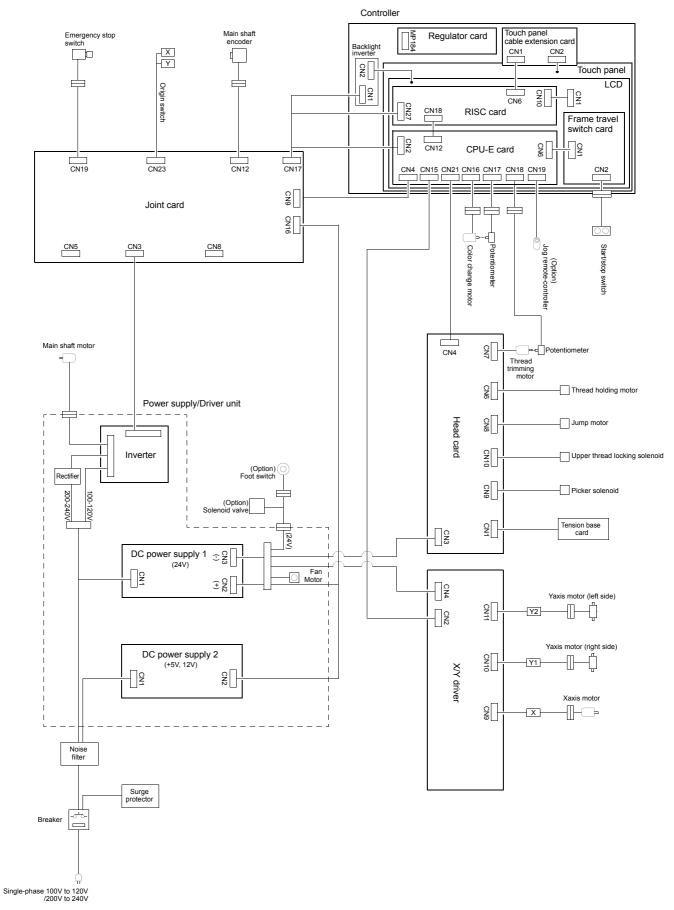
ELECTRO-RELATIVE DRAWING



Layout of electrical parts



Electric system diagram



1st EditionAugust, 20012nd EditionMarch, 20023rd EditionFebruary, 20034th EditionOctober, 2003

Manufactured by: Tokai Industrial Sewing Machine Co., Ltd.

NO.1800, Ushiyama-cho, Kasugai, Aichi-pre., 486-0901, Japan Telephone:568-33-1161 Fax:568-33-1191

Distributed by: Tajima Industries Ltd.

19-22, Shirakabe, 3-chome, Higashi-ku, Nagoya, 461-0011, Japan Telephone:52-932-3444 Fax:52-932-2457

Authorized Distributor: